MINIATURE TRI-PHASIC™ DIGITAL MULTIMETER

MODEL 245KS

WESTERN ELECTRIC COMPANY

MODEL KS-20599 L4

Instruction Manual

WESTERN ELECTRIC COMPANY

KS-20599 L402

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MINIATURE TRI-PHASIC™ DIGITAL MULTIMETER

MODEL 245

CONTROLLED DOCUMENT

Instruction Manual

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DATA PRECISION CORPORATION

1st EDITION APRIL 1974

FOREWORD

Instruction Manual KS-20599 L402 contains information for the operation and maintenance of Digital Multimeter KS-20599 L4, a line and battery operated portable 4½-digit multimeter, including information on test leads, KS-20599 L403, charger and line cord assembly, KS-20599 L404 and leather carrying case, KS-20599 L405.

Digital Multimeter KS-20599 L4 is a special configuration of Data Precision Model 245 DMM, and the information on the Operation, Principles of Operation, and Maintenance for the DMM 245 has been updated for the KS-20599 L4 as presented in this instruction manual. References to Model 245 DMM, as used in this manual, are therefore descriptive of the KS-20599 L4 instrument.

The manual contains additional information for the KS-20599 L403 and KS-20599 L405 items (test leads and carrying case, respectively), which are specifically prepared for the Western Electric Company configuration.

PROPRIETARY NOTICE

The information contained in this publication is derived in part from proprietary and patent data of the Data Precision Corporation. This information has been prepared for the express purpose of assisting operating and maintenance personnel in the efficient use of the Model 245 Digital Multimeter, and publication of this information does not convey any rights to reproduce it or to use it for any purpose other than in connection with the installation, operation, and maintenance of the equipment described herein.

WARNING

Model 245 DMM is battery powered and contains high voltage converters. Therefore, removal of high voltage levels is not assured until the battery module is removed and until the high voltage points are grounded.

CONTENTS

1 INTRODUCTION

1.1 GENERAL
1.2 OPERATING AND DISPLAY FEATURES
1.3 SPECIFICATIONS

2 OPERATION & CALIBRATION

2.1 GENERAL
2.2 UNPACKING
2.3 KEY POINTS ON YOUR MODEL 245 DMM
2.4 OPERATING PROCEDURES
2.5 CALIBRATION
2.6 APPLICATION NOTES

3 PRINCIPLES OF OPERATION

3.1 INTRODUCTION
3.2 OVERALL BLOCK DIAGRAM
3.3 INPUT SIGNAL CONDITIONING
3.4 TRI–PHASIC A/D CONVERTER (ANALOG PORTION)
3.5 END OF CONVERSION AND POLARITY SENSING
3.6 A/D CONVERTER (DIGITAL SECTION)
3.7 DISPLAY
3.8 ISO-POLAR REFERENCE GENERATION
3.9 DC/DC CONVERTER

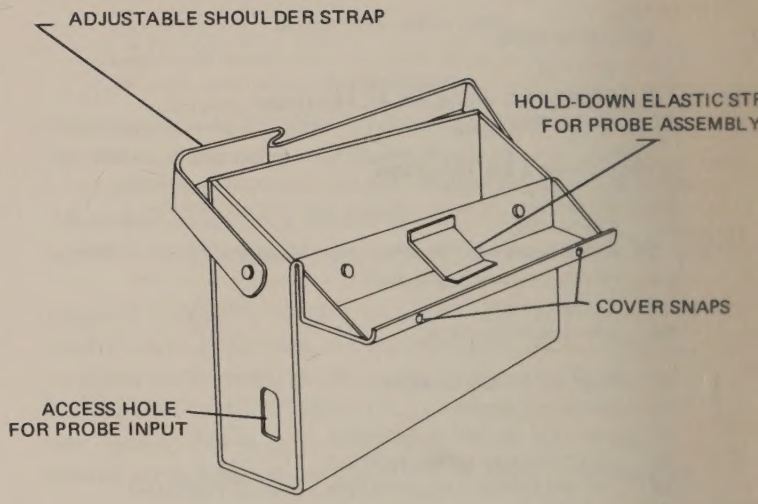
4 MAINTENANCE

4.1 GENERAL
4.2 TROUBLE SHOOTING FLOW CHART
4.3 TEST POINTS
4.4 CLOSED–METER TESTS (FIELD MAINTENANCE) TS4-1
4.5 OPEN–METER TEST/MAINTENANCE
4.6 TEST EQUIPMENT
4.7 DC/DC CONVERTER TEST & POWER TS4-2
4.8 REFERENCE VOLTAGE GENERATOR TS4-3
4.9 DIGITAL LOGIC TS 4-4
4.10 A/D CONVERTER & SIGNAL CONDITIONERS TS4-5

5 PARTS LISTS

5.1 MAIN PC BOARD ASSEMBLY
5.2 TEST PROBES ASSEMBLY

6 REFERENCE SCHEMATIC



Frontispiece: Model 245KS Digital Multimeter

Chapter 1

INTRODUCTION

1.1 GENERAL

The Data Precision Model 245 4-½ digit Multimeter (frontispiece) is a miniature, rugged, battery-powered (or line charged battery), portable meter for measuring DC or AC voltage, DC or AC current, or resistance with 0.005% resolution in 21 ranges and with 100% overrange. The Model 245 uses the Data Precision field-proven Tri-Phasic™ analog-to-digital conversion, Isopolar™ referencing, and Ratiohmic™ resistance measurement designs which provide laboratory-grade performance of high accuracy, stability, and reliability.

The Model 245 DMM is complete, including carrying case, wrist strap, test probes, battery pack module containing rechargeable batteries, battery charger and line cord, and this complete instruction manual. In addition, a field manual is furnished, containing operating and field maintenance procedures for assistance in field use. An optional bench stand (Model B40) is available on which to mount the meter at a convenient bench height and at adjustable viewing angle. The Model B40 stand also provides a measure of security for retaining the mounted meter on the test bench. Extra battery pack modules and chargers are also available as optional units to permit extended time to be available for field battery use. See Specifications paragraph 1.3 for details.

1.2 OPERATING AND DISPLAY FEATURES

Model 245 DMM is operated simply by selecting an appropriate full scale range with one front panel rotary switch and a measurement mode with the other. The measured input signal is displayed on 7-segment planar characters, and the polarity of DC measurements is automatically displayed while the decimal point tracks the manual selection of the full scale range.

Measurements up to 100% overrange beyond the full scale will be within the specified accuracy and displayed as for in-range measurements. Overload signals, beyond the overrange limits on any selected range scale, are automatically sensed, and an Overload indication display is presented. The overload display retains the polarity sign and decimal indication, while blanking all the decimal digits. This is a signal to shift to a higher full scale range. The Model 245 circuitry is protected against damage from an overload signal within the limits allowed by the specifications.

A fully charged battery pack module is capable of supplying 6-hours of in-specification operation, and may be recharged fully overnight (12 hours). Moreover, the batteries are always recharging when the battery charger is connected to a line power source, whether or not the meter is in use.

1.3 SPECIFICATIONS

FUNCTIONAL CHARACTERISTICS

(All modes and ranges)

Reading Rate: 2.5 readings/sec.

Polarity: Autopolarity.

Conversion Technique: Triphasic (see page 4).

Overload Indication: Blanking of all digits, leaving polarity and decimal point illuminated.

Overrange: 100%, except on 1000V ranges as noted.

Common-Mode Rejection Ratios (minimum) with 1000Ω source-impedance unbalance:

AC line operation: 120dB at DC. > 100dB at 50 and 60Hz.

Battery operation: At DC, so high as to be virtually unmeasurable. At 50 and 60Hz, when in close proximity to ground (worst case): >120 dB

Common-Mode Voltage: 500V DC (or peak-AC) maximum when connected to AC power line. 1000V DC (or AC peak) maximum on battery operation (for safety).

Normal-Mode Rejection Ratio: 50dB at 50 and 60Hz.

DC VOLTS

Nominal Range	Overrange	Least-Significant Digit
±1.0000 VDC	±1.9999	100μV
±10.000 VDC	±19.999	1mV
±100.00 VDC	±199.99	10mV
±1000.0 VDC	±1000.0	100mV

Input Impedance:
±1.0000 range, > 1000 Megohms; all other ranges, 10 Megohms.

Maximum Voltage (all ranges): ±1000 Volts.

Resolution: .005%

Accuracy (all ranges, including overrange)

24 hours, 23°C ±5°C: ±.03% rdg ±1 l.s.d.

6 months, 23°C ±5°C: ±.05% rdg ±1 l.s.d.

Add Voltage Coefficient of ±0.00001% (0.1PPM) of rdg/Volt . . . significant only on 1000V range.

Temperature Coefficient (0° C to 40° C, all ranges): (±.003% rdg ±.001% f.s.)/°C.

AC VOLTS

Nominal Range	Overrange	Least-Significant Digit
1.0000 VAC	1.9999	100μV
10.000 VAC	19.999	1mV
100.00 VAC	199.99	10mV
500 VAC	500*	100mV

*See maximum voltage limitation, below.

Input Impedance (all ranges): 1 Megohm in parallel with 50pF or less.
Sensing and Calibration: True Average Sensing, calibrated in RMS of sinewave.
Resolution: .005%
Accuracy (6 months, 23°C ±5°C), all ranges:
at 30Hz: ±0.5% rdg ±.02% f.s.
from 50Hz to 1kHz: ±0.08% rdg ±.02% fs.
at 10kHz: ±0.6% rdg ±.02% f.s.
at 50kHz: ±1.0% rdg ±.05% f.s.
(Linearly interpolate between stated points to calculate accuracy at intermediate frequencies.)
Temperature Coefficient (0°C to 40°C, all ranges):
from 30Hz to 1kHz: (±0.01% rdg ±0.002% f.s.)/°C
at 10kHz: (±0.1% rdg ±0.002% f.s.)/°C
at 50kHz: (± 0.15% rdg± 0.002% f.s.)/°C
(Linearly interpolate between stated points to calculate intermediate temperature coefficients).
Maximum Input Voltage (sinewave RMS):
30Hz to 10kHz: 500V
above 10kHz: decreases linearly to 200V at 50kHz
Settling Time (to settle within ±0.1% of final reading for a full-scale step input): 2.5 sec.

ENVIRONMENT

Temperature Ranges: Operating, 0°C to +40°C
Storage, −25°C to +50°C
Humidity: 95% RH max, 0°C to 40°C

PHYSICAL

The Model 245 measures 5½" wide, by 1¾" high, by 3½" deep. It weighs only 1.3 pounds net, and less than 3 pounds packed for shipment.

The leather case inside dimensions are 8" wide, by 5-3/8" high, by 2½" deep. The adjustable carrying strap is 48" long by 3/4" wide.

DC CURRENT

Nominal Range	Overrange	Least-Significant Digit
±1.000mA	±1.999mA	1μA
±10.00mA	±19.99mA	10μA
±100.0mA	±199.9mA	100μA
±1000.mA	±1999.mA	1mA

Maximum Current: Series fuse (2A) rated at 32V.
Nominal full-scale voltage drop across shunts: 100mV.
Resolution: .05%
Accuracy (6 months, 23°C ±5°C):
±1.000mA range: ±0.1% rdg ±1 l.s.d.
±10.00mA range: ±0.1% rdg ±1 l.s.d.
±100.0mA range: ±0.2% rdg ±1 l.s.d.
±1000.mA range: ±0.2% rdg ±1 l.s.d.

Temperature Coefficient (0°C to 40°C):
±1.000mA range: (±0.01% rdg ±0.001% f.s.)/°C
±10.00mA range: (±0.01% rdg ±0.001% f.s.)/°C
±100.0mA range: (±0.02% rdg ±0.001% f.s.)/°C
±1000.mA range: (±0.02% rdg ±0.001% f.s.)/°C

AC CURRENT

Nominal Range	Overrange	Least-Significant Digit
1.000mA	1.999mA	1μA
10.00mA	19.99mA	10μA
100.0mA	199.9mA	100μA
1000.mA	1999.mA	1mA

Nominal full-scale voltage drop across shunts: 100mV.
Sensing and Calibration: True-Average Sensing, calibrated in RMS of sinewave.
Resolution: .05%
Accuracy (6 months, 23°C ±5°C), all ranges:
at 30Hz: ±0.7% rdg ±1 l.s.d.
from 50Hz to 1kHz: ±0.3% rdg ±1 l.s.d.
at 10kHz: ±0.7% rdg ±1 l.s.d.
at 50kHz: ±1.8% rdg ±1 l.s.d.

Temperature Coefficient (0°C to 40°C, all ranges):
from 30Hz to 1kHz: (±0.03% rdg ±0.003% f.s.)/°C
at 10kHz: (±0.12% rdg ±0.003% f.s.)/°C
at 50kHz: (±0.17% rdg ±0.003% f.s.)/°C
(Linearly interpolate between stated points to calculate intermediate temperature coefficients.)

RESISTANCE

Nominal Range	Overrange	Least-Significant Digit
1.0000kΩ	1.9999kΩ	100mΩ
10.000kΩ	19.999kΩ	1Ω
100.00kΩ	199.99kΩ	10Ω
1000.0kΩ	1999.9kΩ	100Ω
10.000MΩ	19.999MΩ	1000Ω

Maximum Test Current (occurs at zero Resistance-Under-Test):

Range	Current
1kΩ	1.8mA
10kΩ	330μA
100kΩ	35μA
1000kΩ	3.5μA
10MΩ	0.35μA

Configuration: Two-wire
Maximum Open-Circuit Voltage: 3.5 Volts
Resolution: .005%
Accuracy (6 months, 23°C ±1°C):
1kΩ range: ±.07% rdg ±1 l.s.d.
10kΩ range: ±.07% rdg ±1 l.s.d.
100kΩ range: ±.07% rdg ±1 l.s.d.
1000kΩ range: ±0.1% rdg ±1 l.s.d.
10MΩ range: ±0.25% rdg ±1 l.s.d.
Temperature Coefficient (0°C to 40°C):
1kΩ range: (±0.005% rdg ±0.001% f.s.)/°C
10kΩ range: (±0.005% rdg ±0.001% f.s.)/°C
100kΩ range: (±0.005% rdg ±0.001% f.s.)/°C
1000kΩ range: (±0.01% rdg ±0.001% f.s.)/°C
10MΩ range: (±0.02% rdg ±0.005% f.s.)/°C
Settling Time (in seconds): 0.7 + 0.3 x Resistance in Megohms.
Maximum Input Voltage: ±115V DC, or 115 AC (RMS).

POWER SUPPLY

The Model 245 is equipped with a module containing six NiCd batteries, capable of providing up to 6 hours of fully reliable operation between charges. Recharging of batteries requires approximately 12 hours. Where 105-125V, 47 to 63Hz line power is continuously available, the Model 245 may be operated from the AC line, without disconnecting the batteries. (Model 245E operates from 230-250V AC, 47-63Hz.)

Power Consumption: Less than 5 Watts (0.75 Watts in battery operation).

ACCESSORIES

Standard equipment furnished with the Model 245KS (KS-20599 L4) includes:

1 Rechargeable Battery Module
1pair test leads – fused, 2A fuse in Red Lead, KS-20599 L403
Operator's manual
Maintenance Manual, KS-20599 L402
Factory-Test Data Sheets
Certificate of Conformance
One-year Warranty
Special Line Cord with built-in charger, KS-20599 L404
Carrying Case, KS-20599 L405

Chapter 2

OPERATION & CALIBRATION

2.1 GENERAL

Your model 245 4-1/2 digit Multimeter has been shipped with a charged battery pack, and should be usable immediately upon opening the box and attaching the probe leads. This chapter contains:

(1) an inventory list of what you should find upon opening your packing carton;

(2) a complete description of the operating controls and indications;

(3) a step-by-step procedure for operating the instrument in any of its 5 measuring modes;

(4) a step-by-step procedure for recalibrating your meter; and

(5) application notes to help you obtain the measurement accuracies of which your meter is capable

2.2 UNPACKING

The Model 245 is shipped in a molded protective fitted container. This manual has been packed in a recess at the top of the outer protective layer, and should be read before attempting to use the meter. When the protective box is opened, you should find the following items inside the flexible fitted carrying case:

(1) Model 245 4 1/2 Digit Multimeter with attached wrist strap and battery pack module inserted;

(2) Line cord with attached battery charger unit;

(3) Test Probes Assembly (Includes 2 ampere fuse)

(4) Certificate of Conformance and Copies of authenticated Factory Test Data Sheets;

(5) Warranty Card;

Carefully examine these articles, noting especially the matching serial numbers of the instrument and the test data. Inspect the packing case and the instrument for any signs of damage during shipment and report immediately to the carrier. Fill out and return the warranty card to register your instrument and to establish your warrantied service interval.

An optional bench stand, additional charger or additional battery pack may have been ordered. These will be shipped in their own containers.

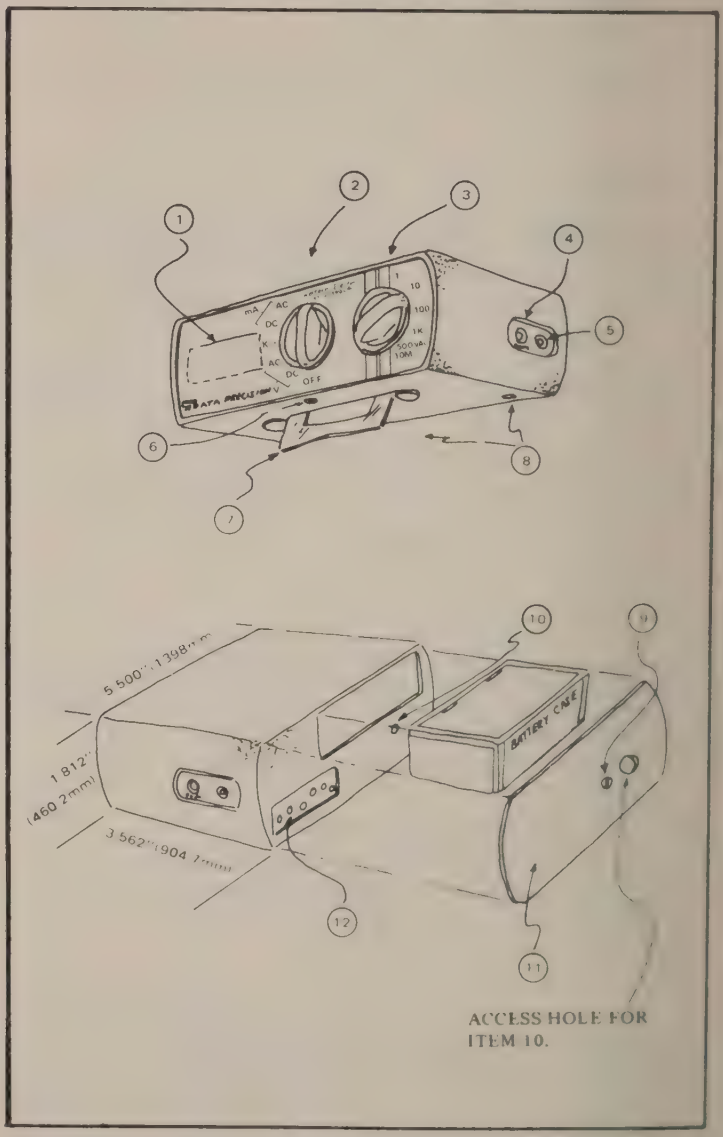


Figure 2-1. Operating controls and indicators, showing access to Battery pack and calibrating adjustments (after removal from leather case).

2.3 KEY POINTS ON YOUR MODEL 245 DMM (FIGURE 2-1)

1.	Display Area	Automatic polarity indication; decimal digits plus overrange "1"; and range-scale selected decimal point display.
2.	Function Switch	Rotary 6-position switch. Selects one of five measuring function or OFF.
3.	Range Switch	Rotary 5-position switch. Selects one of four full scale display values and corresponding decimal points for voltage and current measurements, and one of five full scale values for resistance measurements.
4.	COM *	Receptacle for probe common (or reference) lead.
5.	HI *	Receptacle for probe high (or signal) lead.
6.	Assembly Screw	Slotted screw fastens meter assembly to case.
7.	Flip-Down Tilt Leg	Recessed hinged leg to support meter in tilt position.
8.	Non-skid pads	2 pads to prevent meter from sliding on smooth surfaces.
9.	Screw	Holds rear cover in place
10.	Charger Input	Receptacle for charger input and Battery test point
11.	Rear Cover	Removable cover to permit access to calibrating adjustments, and to remove battery.
12.	Adjustments	6 Full Scale calibrating adjustments

*The two leads are molded into a single assembly, including both HI and COM connectors.

2.4 OPERATING PROCEDURES

2.4.1 General

Operate your multimeter in the following sequence for most efficient use;

a) If line power is to be used, attach battery charger output to meter at rear panel connector; then plug in battery charger to appropriate AC power line. See power data on charger label.

b) Turn the instrument on by selecting the desired measurement function with the Function Mode Switch . . . DCV, ACV, etc.

c) Select the appropriate full scale range . . . 1K, 100, 10, etc.

d) Connect test leads to meter and apply probes to circuit under test.

e) Read display

f) Select different full scale range value for highest resolution capability.

2.4.2 Applying Power

The Model 245 4-1/2 digit multimeter may be operated from power supplied by the internal battery module containing six rechargeable NiCd batteries. Before operation, perform coarse check to determine whether the batteries are charged sufficiently to perform the anticipated measurements by turning on and observing that display is lighted. The batteries will supply up to six hours of in-spec operation when fully charged. Re-charging requires approximately 12 hours. The Model 245 may also be operated from AC line power, where available without disconnecting the batteries, by using the AC charger and integral connecting cable supplied with the instrument. The standard Model 245 is designed to operate from 105-125VAC; Model 245E is designed for 210-250 VAC. When the line cord and battery charger are connected, the batteries are always charging even when the Function Switch is in the off position. A protective circuit prevents overcharging the batteries. For extended field use without access to charging power, an extra battery module is recommended.

Check the battery charge level by using the meter on DCV function and 10 Range. Place the HI probe on the metal ring of the battery charger input (item 10 on figure 2-1). A negative measurement with a value in excess of 7.2 indicates a charged battery.

To use the AC line power, insert cord of KS-20599 L404 through access access hole in the bottom of the leather carrying case. Check proper source source voltage for charger unit; plug in charger to source power.

2.4.3 Selecting Measuring Function

The left-hand, six-position rotary Function Switch turns the meter measuring circuits on, and makes the required internal connections to measure DC volts, AC volts, Kilohms, DC milliamperes, or AC milliamperes. The switch positions are as shown in Table 2-1.

2.4.4 Selecting Full-Scale Range

The right-hand rotary Range Switch selects the full-scale range to be displayed, and simultaneously positions the decimal point for direct reading. The switch positions and the full-scale reading are shown in Table 2-2. Note that the least significant (fifth) digit is blanked for current measurements. Note also that the 10MΩ position is used only for resistance measurements.

2.4.5 Connecting the Inputs

Connect the probes: red probe lead to the HI receptacle and the black probe lead to the COM receptacle of the meter. Measurements made at the sensing ends of the probes will be the value of the HI input with respect to the COM input. If the meter reads +17.724 Volts DC, then the HI (red-lead) terminal is 17.724 Volts higher in potential (more positive) than the COM (black-lead) terminal.

Table 2-1 Function Switch Mode Selection

FUNCTION SWITCH POSITION (clockwise from OFF)	PARAMETER MEASURED (or Instrument Status)
OFF	Disconnects power from battery to meter; Retains charging action to battery if line cord/battery charger are connected.
DCV	DC voltages up to 1,000 volts
ACV	Up to 500 VRMS of true-average-calibrated in RMS AC voltage, from 30Hz to 10KHz, decreasing linearly to 200 V at 50KHz.
KΩ	Resistance in kilohms up to 1000 kilohms, and in megohms up to 20 megohms, with maximum open circuit voltage of 3.5 volts, and able to withstand connected external voltage of ±115V DC or 115V AC RMS. Can be >115V in higher ranges.
DCmA	Direct Current in milliamperes, up to 2,000mA, protected by 2-ampere fuse rated at 32V in red imput probe.
ACmA	Alternating Current in milliamperes. Up to 2,000mA of true average value calibrated in RMS of equivalent sinewaves.

Table 2-2 Range Switch FSR Selection

Switch Position Marking (Clockwise from top)	Nominal Full Scale	Overrange	Units		
			Voltage	Current	Resistance
1.0	.9999	1.9999	V	mA	KΩ
10	9.999	19.999	V	mA	KΩ
100	99.99	199.99	V	mA	KΩ
1K	999.9	(Note 1)	V	mA	KΩ
10MΩ	9.999	19.999	–	–	MΩ

*Least significant digit blanked on current readings; and additional 100% overrange possible.

(Note 1): See specification para 1.3 for overrange limits on these scales.

2.4.6 Reading the Display

DC polarities are automatically indicated on the display, and reflect the polarity of the HI signal with respect to the COM.

Overrange values up to 100% above the selected full scale range will be measured and displayed. The maximum indication is 19999 with the appropriate decimal point location (and a blanked right hand digit on current measurements).

Overload measurements of more than 100% above the selected full scale range are indicated by a blanking of all digits, leaving only the polarity of overload and decimal point display lighted. For example, if the applied signal is more than +19.999 volts on the 10 volt full scale range, only the + sign and the decimal point will appear.

2.5 CALIBRATION

2.5.1 General

The Model 245 Digital Multimeter is factory calibrated and burned-in prior to shipment, and is designed to remain in calibration for a minimum of 6 months before recalibration procedure should be required. The complete set of factory test data sheets for each instrument are shipped with the meter.

2.5.2 Test Instrumentation and Preparation

When recalibration is required, test standards of the following range and accuracy should be used:

DC Volts:		0 to	1.0000V ± 0.01%
AC Volts:	at 100 Hz:	0 to	1.0000V ± 0.05%
	at 20 KHz:	0 to	1,000. V ± 0.10%

Calibrating adjustments are accessible through the rear panel, behind the removable cover plate in the lower left hand corner. Lift out the cover panel by inserting a small tool in the hole and lifting out. The circuit reference designations are stamped on the meter panel for the six full scale range adjustments.

NO ZERO ADJUSTMENT IS EVER REQUIRED ON ANY MEASUREMENT FUNCTION OR RANGE SCALE AND NONE IS PROVIDED.

2.5.3 Calibration Procedures

Perform the adjustments in the sequence listed below. Apply test inputs of an amplitude and frequency as close as possible to those listed. Adjust the designated control until the display indicates the exact value of the test input applied. If the only test standard available does not provide the full scale values shown in the table below, then the closest value to the specified input should be used, and the control adjusted for that display value. It is desirable to use input signals of at least 50% of full scale if that option is available.

Table 2.3 Calibration Adjustments

Function Select	FSR Range Select	Test Signal	Adjustment Marking
DCV	1.0	+ 1.9000 VDC	R10
ACV	1.0	100 Hz, 1.9000 V RMS	R4
ACV	1000	20 KHz. 200.00 V RMS	C7
ACV	100	20 KHz, 100.00 V RMS	C3
ACV	10	20 KHz, 19.000 VRMS	C2
ACV	1.0	20 KHz, 1.9000 VRMS	C1

Adjust until the display indicates the value of the test input.

WARNING

Use insulated calibration tool.
High voltage may be present at calibration points.

Note that calibration of other function modes is implicit in the adjustments made according to the table above. This results because the circuit design utilizes the same attenuation networks in common among the different signal conditioning functions.

2.6 APPLICATION NOTES

2.6.1 General

Optimum performance is obtained from your Model 245 by observing a number of precautions in establishing the test measurement conditions. The few hints included in this paragraph are only indicative of the types of measuring environment problems which may influence the meter performance. It is suggested that the user add his own application aids in the space provided.

2.6.2 Avoiding Ground Loops (Making Grounded Measurements)

If the battery charger/line cord is connected, a potential difference may exist between the "ground" of the power source and the "ground" of the measured circuit. This difference of ground potentials may set up ground-loop currents and affect the measured values although the instrument will reduce their effects significantly (CMRR = 120dB, NMR = 50dB). The ground loop effects can be avoided almost completely by operating the meter on batteries

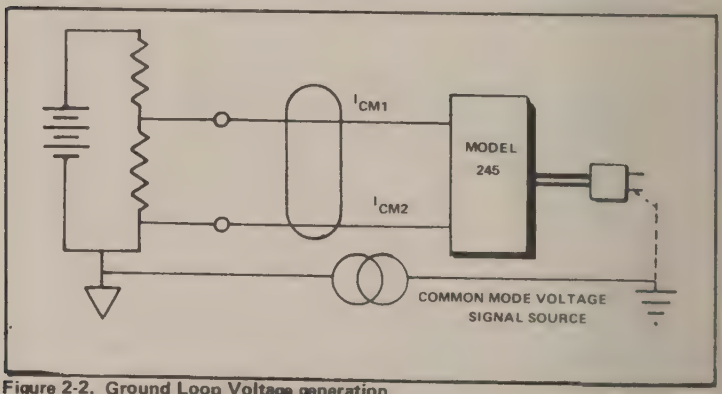


Figure 2-2. Ground Loop Voltage generation

2.6.3 Making "Floating" Measurements

In a floating measurement, such as in figure 2-3, it is possible to introduce a common mode voltage by reactive coupling through the AC power line when that source of Model 245 power is connected. As in paragraph 2.6.2, although this effect is small, it may be avoided almost completely by disconnecting the AC power source and reverting automatically to battery power.

2.6.4. Making High Resistance Measurements

When making measurements of very high impedance sources, as when required to measure resistance on the 10MΩ full scale range, the input circuit may be susceptible to noise. The effect of voltage-producing noise fields on the probe leads may be sufficient to introduce significant changes in the least significant digit of the display.

Measurement errors may be kept to a minimum under these circumstances by keeping the leads as short as possible (do not use any extensions on the probes), and by twisting the probe leads so as to equalize any field effects on the signal input leads.

NOTE: **It is good practice to twist probe leads whenever possible in order to equalize any field effects on the signal input leads.**

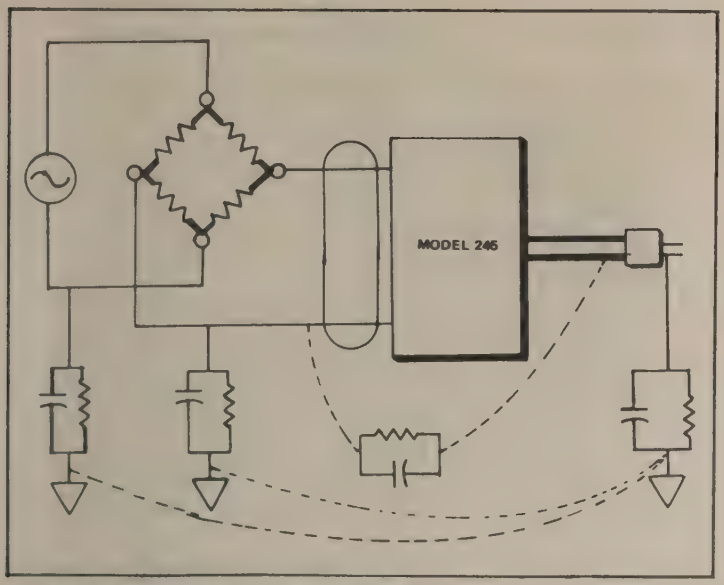


Figure 2-3. Induced AC common mode voltages

2.6.5 Making Very Low Voltage Measurements.

Problems may arise when measuring very low voltages because of the differences in temperature of the probe contact points. Both probes are plated brass, and if the HI probe is in contact with copper in a high ambient temperature, for example, in a computer tape drive mechanism, while the COM probe is grounded at a very much cooler steel cabinet frame, then a difference in emf of several hundred microvolts may result, changing the least significant digit. In order to minimize such errors, connect the probes wherever possible at approximately the same temperature.

2.6.6 Making Complex Waveform AC Measurements

The Model 245 is calibrated in equivalent RMS values of a sine wave whose average value is the value actually measured by the multimeter, Thus, if a non-sinusoidal waveform is applied at the input the displayed value may be in error, depending upon the extent of the difference in waveforms.

The Model 245 develops a DC voltage from an AC input by half-wave rectification and the ratio of RMS to average halfwave of a sine wave is 2.2:1. The corresponding ratios for other sample waveforms are included in Table 2-4.

Table 2-4. Multiplying Factors for Non-Sinusoidal Waveform Measurements

WAVEFORM	Model 245 AVG VALUE	TRUE RMS VALUE	MULTIPLY DISPLAY BY
	.707A	.707A	1.0
	1.11A	1A	0.903
	555A	574A	1 034

Chapter 3

PRINCIPLES OF OPERATION

3.1 INTRODUCTION

Model 245 DMM is triggered automatically to initiate the 3-phase measurement cycle. During phase 1 the meter circuits are automatically servoed to determine the correction for the accumulated zero offsets in the analog integrator loop. In phase 2 the signal to be measured, which has been conditioned according to the type of signal (AC, DC, Ohms) and selected range scale (X1, X10, . . . X1000), is connected in series with the zero offset correction to the dual slope A/D converter integrator which integrates the conditioned input for a fixed time interval of 100 milliseconds. After the fixed time interval of phase 2, phase 3 begins in which the input signal is disconnected from the A/D converter, and in its place a reference signal of opposite polarity and fixed magnitude, is connected in series with the zero offset correction. The integration of the reference signal continues in phase 3 until this second ramp of the dual ramp A/D converter reduces the charge on the integrating capacitor to zero. The zero level on the integrating capacitor is sensed, and it indicates the End of Conversion (EOC) if it occurs in 200 msec or less during phase 3. If there has not been an EOC signal within 200 msec in phase 3, the meter interprets this as an overload condition and quickly ends phase 3 via a fast time discharge and initiates phase 1 to restart the conversion cycle. The fast time constant introduced into the capacitor discharge circuit aassures that the auto-zeroing integration in phase 1 will start from zero conditions. The overload sense circuit also initiates the development of logic control signals for the overload display.

3.2 OVERALL BLOCK DIAGRAM

As shown in Fig. 3-1, the meter consists of the following major functional sections:

A. Input Signal Conditioner.
B. Tri-Phasic™ Analog-to-Digital Converter (Analog Section).
C. Tri-Phasic™ Analog-toDigital Converter (digital section).
D. Timing Generator.
E. Display.
F. Reference Generator.
G. DC/DC Converter.

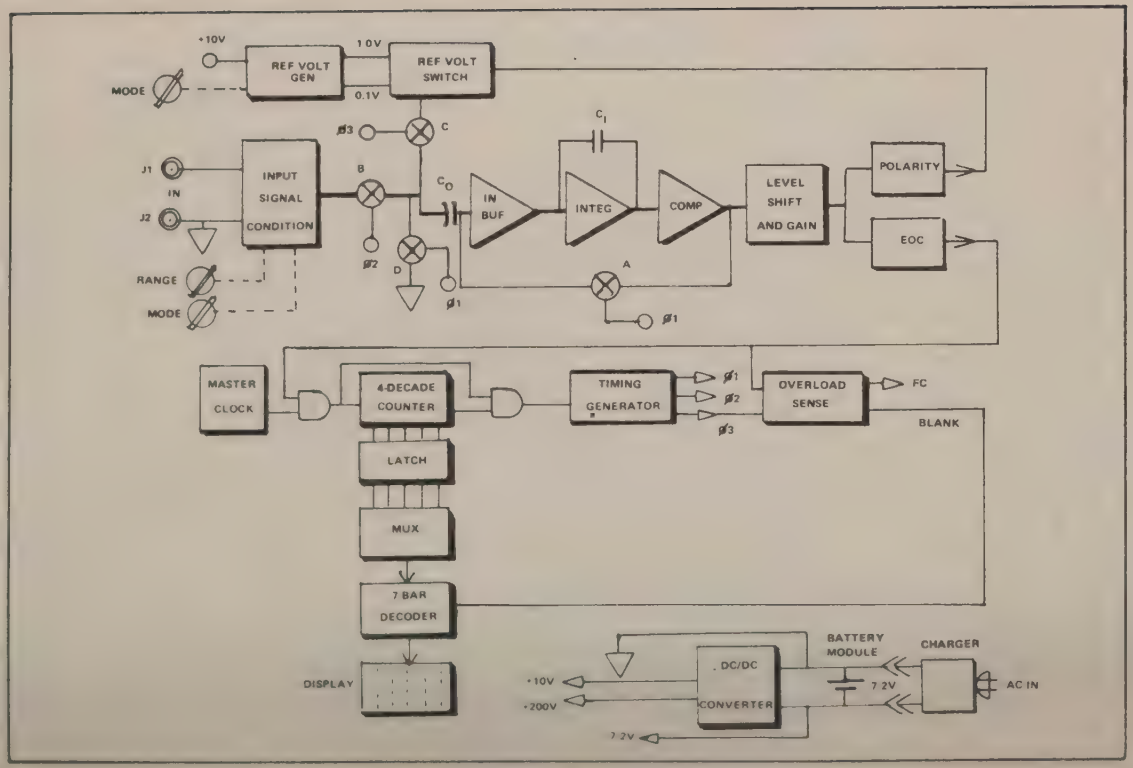


Figure 3-1. Model 245 DMM Simplified Block Di

3.2.1 Input Signal Conditioner

The input signal conditioner receives the connected input voltage or current and develops a scaled voltage output in accordance with the selected meter function and selected full-scale range. The signal-conditioner output is 1.0VDC full scale when the unknown input is a full scale voltage signal on any range or is 0.1VDC full scale when the unknown input is a full scale current signal.

The input signal conditioner section remains linear for the full 100% of overrange input signal values and includes protective elements for overload conditions beyond the specified overload capabilities.

3.2.2 A/D Converter (Analog Section).

The analog section of the Tri-Phasic Analog-to-Digital Converter includes the input buffer stage, the integrator, and the comparator. They function as follows during the three phases of Tri-Phasic operation:

Phase 1

During Phase 1 the analog section automatically zeros the unit to correct for the zero offsets inherent within the analog functioning elements. During this phase, switch A and switch D are closed, removing the conditioned input, while the input to the high input impedance unity gain amplifier is grounded. As a result, the closed loop servos the output of the A/D comparator to near zero. At that time a charge will have been developed across the memory capacitor, C_o, which balances the sum total of all the individual offsets generated within the loop.

Phase 2

At the start of Phase 2, switches A and D open, and switch B closes. In the open position of switches A and D, the analog section retains the offset voltage on memory capacitor C_o as a correcting value which will be combined algebraically with the input signals and the algebraic sums integrated in Phase 2 and Phase 3.

Switch B, which remains closed during Phase 2, connects the input signal conditioner output to the unity gain buffer. Its output is integrated for a fixed time of 100 milliseconds as controlled by the timing generator in the digital control logic. The charge developed on the integrating capacitor C_I is therefore proportional to the magnitude of the input signal, and the output of the high-gain comparator amplifier will be at a saturation level of opposite polarity to the meter input signal.

Phase 3

At the start of Phase 3, switch B opens, removing the conditioned input signal from the unity gain amplifier. At the same time (start of Phase 3), the polarity sense function of the digital section determines the polarity of the comparator output and transmits a control signal to the reference selection switching network thereby connecting the correct polarity of the reference voltages through Switch C to the unity gain amplifier for integration during Phase 3. The reference voltage integrated during Phase 3 decreases the charge on integrating capacitor C_1 until the output of the high gain comparator changes polarity. This change in comparator output polarity indicates end of conversion and is sensed at the output of the level shift and gain stage of the digital section to indicate the start of Phase 1 through the timing generator logic. The cycle repeats. If the charge on C_1 is not reduced to zero in the time interval allowed for full overrange measurements, the digital control logic initiates the overload actions in the multimeter, as explained later. It should be noted that the zero offset is generated and the storage capacitor charge is updated in each conversion cycle. Also, note that the stored voltage representing the corrected zero is introduced into the analog section for both the unknown integration and the reference integration, thereby removing the zero effects from both the charging and the discharging actions on C_1.

3.2.3 A/D Converter (Digital Section).

The digital section of the A to D converter includes the phase timing generator, the comparator output sensing circuit, the counter and code converter circuit. The latter consists of a monolithic chip on which are mounted the four-decade counter, latch, multiplexer, and seven-bar decoder, as well as an internal oscillator and digit selecting counter associated with their operation. The function of the elements on the chip is to convert the time interval needed by the analog section in Phase 3 to reduce the charge of the integrating capacitor to zero into a count which will be displayed as the measure of the input signal. The four-decade counter increments from zero at the start of Phase 3 and builds up a count at the rate of 100 KHz. When the end of conversion signal is developed, incrementing is stopped, and the binary values in the counter are transferred to the latch, where they are held while the multiplexer and decoder translate the binary value into the appropriate lighted segments of the display. Should the signal at the input exceed the 100% over-range value, the end of conversion indication will not be generated before the completion of 20,000 counts. This is the condition for an overload, and the overload sense circuit of the digital section then performs two actions:

a) It develops a blanking signal which blanks all the display digits (not including decimal point and sign) and, in addition,

b) Develops a fast charge signal (FC) which changes the time constant on the integrating capacitor circuit to reduce its charge quickly to zero so that adequate time remains in phase 1 to develop the correct zero correction. If a fast discharge (TC) had not been introduced, it would have been possible for the residual charge to affect the zero correction and to increase the time to recover from overload.

3.2.4 Timing Generator Circuit

The time generator section consists of a master clock, a four-digit counter (the same element as described previously), and a number of logic gates and flip-flops. The function of the timing generator section is to produce the synchronizing control signals which define phases 1 and 2, and in conjunction with the EOC sensing, phase 3. The timing signals are derived from the master clock frequency of 100 KHz which is counted down by the four-digit counter into segments of 100 milliseconds each by gating each 10,000 count carry from the counter. The action of the subsequent logic produces the timing signals in the relationship shown in Fig. 3-2. Fig. 3-2 also shows the charging and discharging of C_1 in these phases.

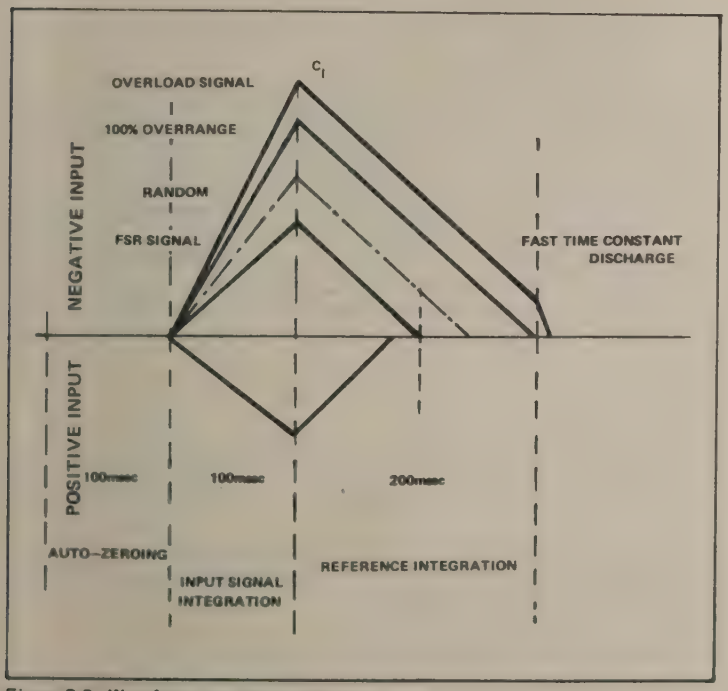


Figure 3-2. Waveforms and Timing Diagram

3.2.5 Display

The display consists of four full decades of seven-segment characters, a fifth element which may take a character of "1" or remain blank, and an element for indicating the polarity of the input signal. The decimal point position is controlled directly by the manual range selection.

3.2.6 Reference Generator

The Iso-polar™ reference generator provides a precise 1.0 or 0.1 volt level to be connected to the analog input for Phase 3 operation. The selection of 1.0 or 0.1 voltage level is accomplished by the mode selection. The Iso-polar action features the development of a precise positive reference voltage and then through precise passive elements and controlled switching obtains positive or negative references with equal magnitudes. The reference generator is powered by the +10 volts received from the DC/DC converter, and also generates the precision +7.2 volts as needed within the unit. The reference voltage generator section also includes the circuitry for ratiohmic measurement connections to be described later.

3.2.7 DC/DC Converter

The power for the meter is obtained from a 7.2 volt battery supply which is connected as a negative voltage source. A plug-in battery charger, provided as standard equipment, maintains the −7.2 volt charge whenever the charger is connected to line power, whether or not the meter is on. The DC/DC converter is connected to the −7.2 volt battery supply only when a measuring function is selected, and develops nominal +200 volts for the display lamp power and +10 volts for the analog amplifier units. The −7.2 volts for the digital logic and for the analog amplifier units are supplied directly by the battery.

Each of the major functional blocks will now be described in detail with reference to simplified schematics derived from a complete detailed schematic enclosed as a foldout in the back of this manual.

3.3 INPUT SIGNAL CONDITIONING

3.3.1 DC Voltage Signal Conditioning

The circuitry involved in conditioning a DC voltage input is shown in Figure 3-3.

The input at J-1 is the high side of the voltage to be measured, while J-2 represents a common to which all measurements are referred. The illustration indicates the connections made by the front panel circuitry selector switch when in DC Volts mode and for scale "X1". The input is direct for the X1 scale, and is attenuated by the matched precision resistor network in the other scales

3.3.2 AC Voltage Signal Conditioning

Figure 3-4 illustrates the circuit as connected when the AC voltage is selected by the function switch and when the "X1" range scale is selected at the range switch. As in all measurements, one side of the input is connected through J-2 or the common reference for the input measurement.

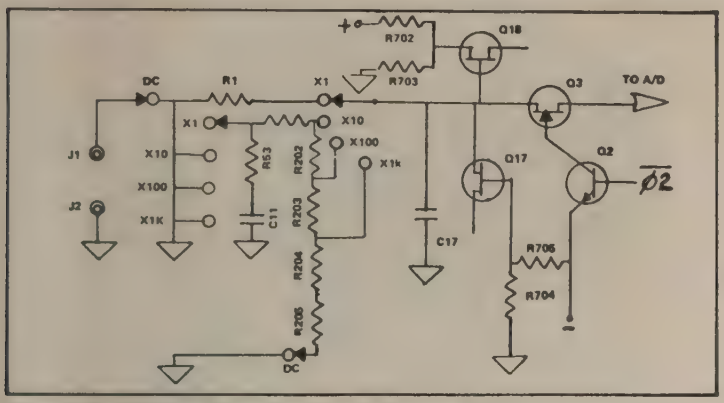


Figure 3-3. DC Voltage Signal Conditioning Schematic

The feedback path around high gain Z1 accomplishes the designed input attenuation as selected by the range switch. The components in this attenuator network are the same as for DCV conditioning, but connected as shown for ACV. The output of Z1 is connected to a half-wave rectifying circuit through a gain stage which is nominally set for a gain of 2.22 so that the average value obtained as a result of the rectification represents the RMS value of an equivalent sine wave input. The filtered output of the rectifying circuit is the input to the A/D converter section. Thereafter, the circuit operation is the same as for measuring DC voltage, while the displayed result is in terms of the RMS value of the AC input.

3.3.3 Resistance Input Signal Conditioning

The resistance value to be measured is connected across input terminals J_1 and J_2, and the simplified schematic illustration of Figure 3-5 is drawn to indicate the circuit connections when in resistance measurement mode.

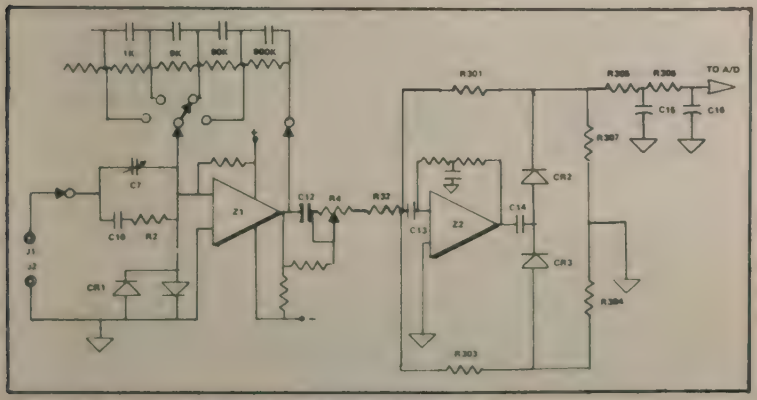


Figure 3-4. AC Voltage Signal Conditioning Schematic

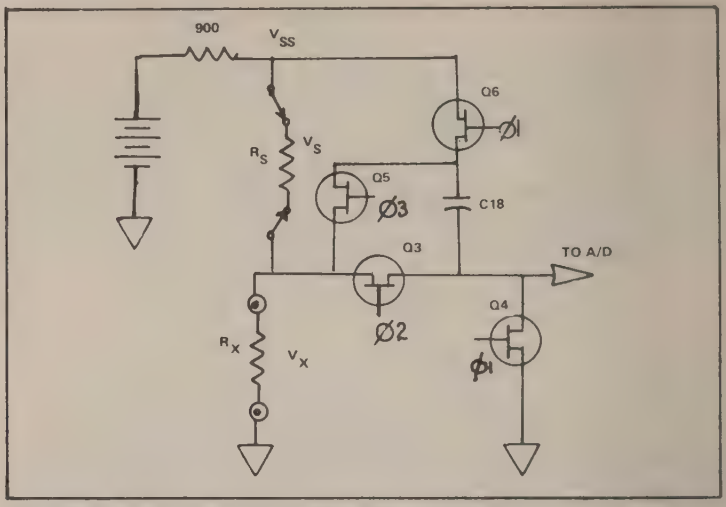


Figure 3-5. Resistance Measurement Signal Conditioning

In the Ratiohmic™ technique shown in the simplified schematic of Figure 3-5, the current I, passing through the series combination of the selected standard resistance Rs and through the unknown resistance R_X generates the voltage drops identified in Figure 3-5 as V_X and V_S.

The values of voltage connected to the A/D buffer input depend upon the controlled switch closures of Q3, Q4, Q5, and Q6. During Phase 1, Q6 and Q4 are closed. This provides a charging path for capacitor C18 which charges to the potential V_{SS} equal to $V_S + V_X$. During Phase 2, Q3 is closed and the voltage V_X across R_X is connected to the A/D buffer input.

During Phase 3, switch Q5 is closed and this action places the high side of the capacitor at the V_X level while the low side is connected to the A/D buffer input. The low side is then $V_S + V_X - V_X = V_S$. The integration proceeds until the charge on the integrating capacitor (not shown in Fig. 3-5) is reduced to zero as in voltage conversion. The A/D converter measures the ratio of $V_X/V_S = R_X/R_S$ and displays the result calibrated in kilohms according to the selected full scale range.

3.3.4 DCmA Input Signal Conditioning

Fig. 3-6 is a simplified block schematic of the circuit as connected when the function mode switch is in the DCmA position and when the range switch is in the X1 position. The input is connected across J1 and J2, with J2 functioning as the common reference for this and for all measurements.

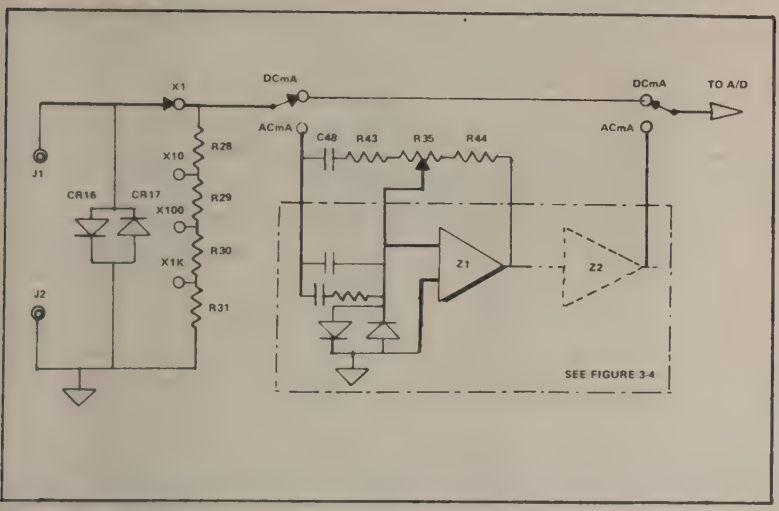


Figure 3-6. Current Signal Conditioning Schematic

The network R28, R29, R30, R31 forms a precision shunt for sealing the input current to an appropriate value of input AC voltage depending upon the scale selected. The output of the shunt network is the scaled DC voltage which is connected to the A/D converter input. Thereafter, the circuit performs exactly as for DC voltages.

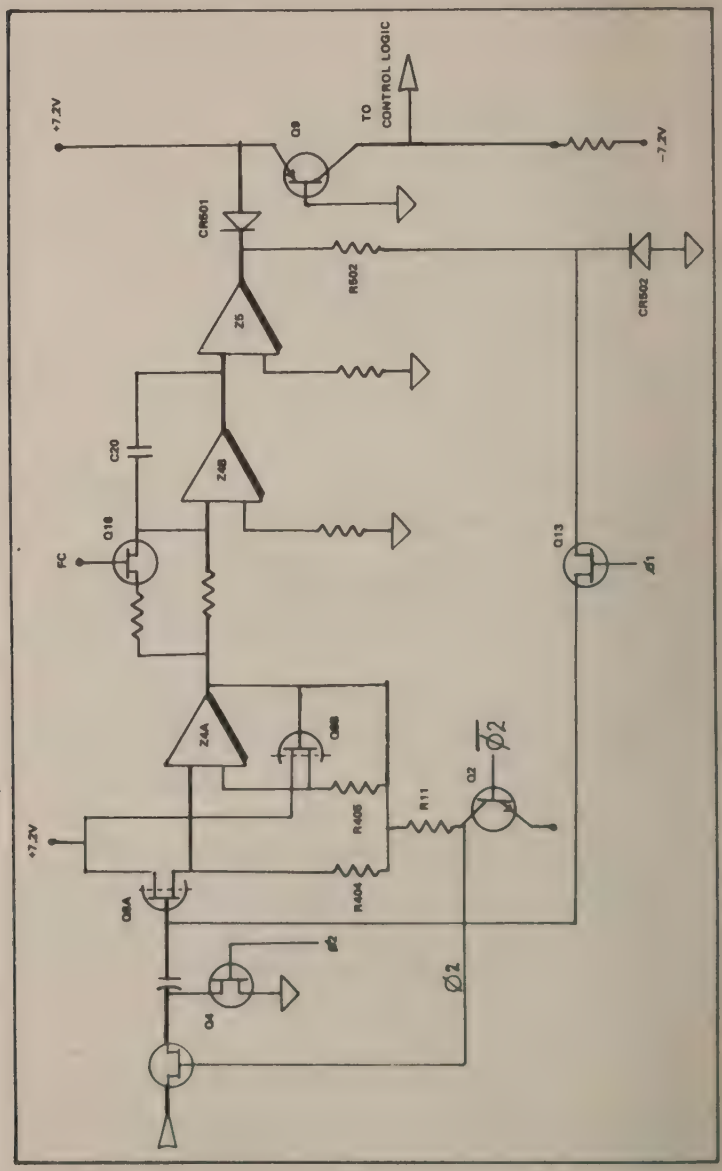
The protection devices for overload in the DCmA mode are CR13 and CR14 pair of diodes whose breakdown voltages provide a threshold to limit the input signal to 1 Volt.

3.3.5 ACmA Input Signal Conditioning

Fig. 3-6 also illustrates the connections of the function mode switch for the ACmA measurement mode. As illustrated, the AC milliampere input signal is first connected to the shunt network becoming a voltage input which is then scaled in the feedback path of Z1 and Z2, the two stages of amplifier and rectifier as described for the AC voltage signal conditioning. The scaled DC signal is then connected to the A/D buffer input. R35 is a factory adjustment needing no further field adjustment.

3.4 TRI-PHASIC A/D CONVERTER (ANALOG PORTION)

The simplified schematic of Fig. 3-7 illustrates the operation of the analog portion of the Tri-phasic analog-to-digital converter. This portion consists of three major operational elements (1) unity gain buffer amplifier Z4A, preceded by matched high impedance input FET's Q8A and Q8B, (2) high-gain operational amplifier Z4B, connected as an integrator with integrating capacitor C20 in the feedback path, and (3) high-gain comparator Z5 driving to saturation for a small difference in potential between the integrator output and the ground reference. During phase 1, the three


+7.2V
Q9
TO CONTROL LOGIC
-7.2V
CR501
R502
CR502
Z5
C20
Z4B
Q10
FC
Q13
Ø1
Z4A
Q8B
Ø2
Q12
R405
R11
+7.2V
Q8A
R404
Ø2
Ø2
Q4

elements are connected in a closed loop by FET switch Q13. The comparator output is followed by a level shift and gain stage, consisting of diode CR501 and transistor Q9 for proper level and drive values in subsequent logic circuitry.

As controlled by signals from the digital portion of the converter (to be described later) the analog portion (1) automatically updates the zero correction, (2) integrates the conditional input (scaled according to the function selected so that 1.0 volts is full scale for voltage measurements and 0.1 volts for current or resistance measurements) and (3) integrates the reference voltage of appropriate polarity and full scale magnitude.

3.5 END OF CONVERSION AND POLARITY SENSING

The digital control logic for sensing EOC and input signal polarity is illustrated in the simplified schematic of figure 3-8.

At the start of phase 3, the state of flip-flop Z7B indicates the polarity of the input signal integrated during phase 2. If the unknown input signal were negative, the D input to Z7B would be at the ground level; if the unknown meter signal were positive, the D input to Z7B would be at the −7.2 volt level. At the phase 3 clock pulse to flip flop Z7B, the D input is transferred to the Q output, and the control level appears on the appropriate polarity switch-selecting line. As shown in the illustration, phase 3(−) implies selecting a positive reference for a negative input signal, and phase 3(+) implies selecting a negative reference for a positive meter input signal.

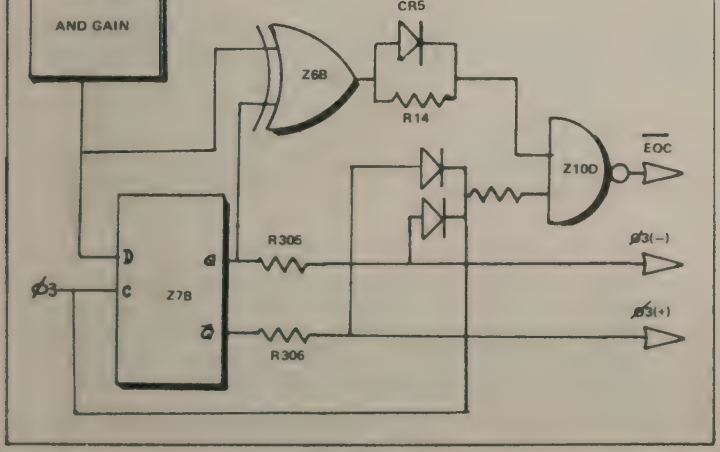


Figure 3-8. EOC and Polarity Sensing Schematic

One or the other of Z7B outputs must be a high level signal input to gate Z10D while the other input signal to Z10D comes from exclusive OR gate Z6B. Because both inputs to Z6B are the same polarity at the start and during phase 3, the output of Z6B is at low level. As soon as the polarity of the comparator output changes, gate Z6B responds by delivering a high output level, and thereby causes gate Z10D to issue a low level signal which signifies the end of conversion, EOC.

3.6 A/D CONVERTER (DIGITAL SECTION) AND TIMING GENERATOR

The digital logic section of the Tri-phasic A/D converter instruments the programming control functions to signal the start of Phase 1, Phase 2 and Phase 3 of each conversion cycle. Phases 2 and 3 control signals are derived from clock generated pulse trains, while Phase 1 may be initiated by the end of conversion or from the clock chain if input is an overload signal. The digital logic section also generates the control signal for selecting the appropriate polarity of reference voltage for Phase 3 integration and for display purposes.

The timing generator consists of a stable tuned free-running clock oscillator whose gated output drives a 4-decade counter and from which the digital control logic develops the program control signals.

Both the digital section and the timing generator functions are illustrated in the simplified block schematic of Figure 3-9. The operation of the circuit illustrated in this block diagram may be understood by tracing the development of the waveforms as shown in the timing waveforms of Figure 3-10.

The change in output polarity from the comparator occurring in Phase 3 is the indication of end of conversion, EOC. It is converted to a negative-going pulse at the output of Z10D (figure 3-8), and serves two functions:

a) The leading, negative-going edge blocks the clock output, preventing a count pulse from further changing the value in the counter.

b) The positive going edge enables the transfer from the counter to the latch of the value in the counter at that time. (See Reference Schematic).

The $\overline{\text{EOC}}$ pulse is also gated by exclusive OR gate Z6A to reset flip-flop Z8B at the DR input. This action causes the Q output of Z8B to go low, and, in combination with the Phase 2 signal at the input to Z6E, generates the digital control signal for the start of Phase 1. Note, in Fig. 3-10, that both $\overline{\text{Phase 2}}$ and Phase 3 signals are high during Phase 3, and thus the exclusive OR gate Z6E remains low until one of the inputs goes low.

Should the counter reach a second carry while Phase 3 is in process, indicating an overload condition, the digital control logic will respond as follows

a) The outputs of Z9A and Z9B will cause flip-flop Z7A to generate the overload blanking control signal connected to the 7 segment converter of the display logic.

b) The gate formed by R40 and CR18 produces a high level output for the FC signal. The FC control signal activates FET switch Q16 (figure 3-7) and introduces a fast time constant in the integration path in order to reduce the remaining charge on integrating capacitor C20.

DISPLAY* 3.7

The display comprises two segments DS-1 and DS-2, providing the capabilities for 4 full decade digits, a most significant digit which is "1" or blank, automatically selectable positive or negative polarity indication, and five selectable decimal point indications.

The decimal digits are made up of appropriate combinations of seven segments driven one digit at a time by a multiplexed BCD to 7-segment converter logic. The converter is synchronously connected to the latched values at the same time +200V power is applied to the selected digital display position. The counter, latch, multiplexer, and 7-segment converter, as well as the scanning oscillator, digit select logic and buffer for control of the high voltage are all contained in the LSI module.

The decimal point selection is made directly to the display by the manually selected range switch. The selected range causes the appropriate decimal point control line to be grounded, lighting that decimal point display. The polarity indication is similarly actuated directly at the display, but by the polarity select digital control signals.

The blanking action is effective through the code converter, and operates on the decimal display digits. The polarity and the decimal point indications are not affected by the overload control.

When measuring current, the mode selector switch acts to block the application of high voltage to one decade, permitting only a 3 1/2 digit display for measuring current on any range scale.

The Display assembly is a non-repairable, replaceable assembly.

*See Fold-Out Reference Schematic

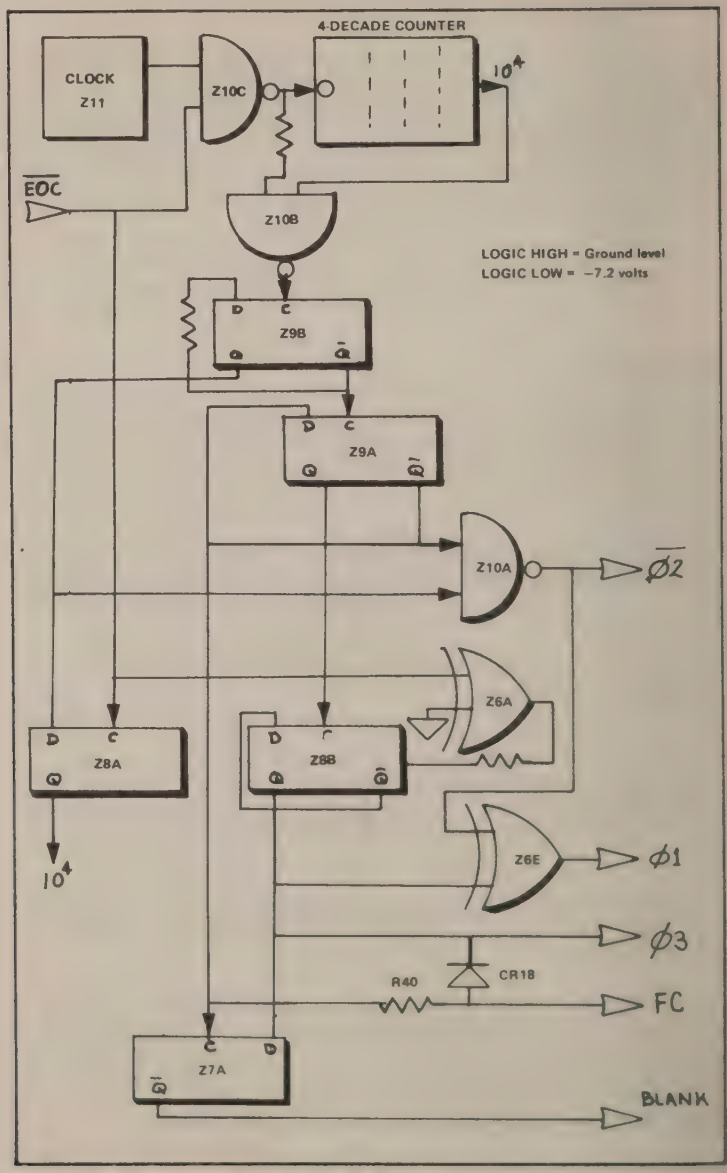


Figure 3-9. Digital Control Logic Block Diagram

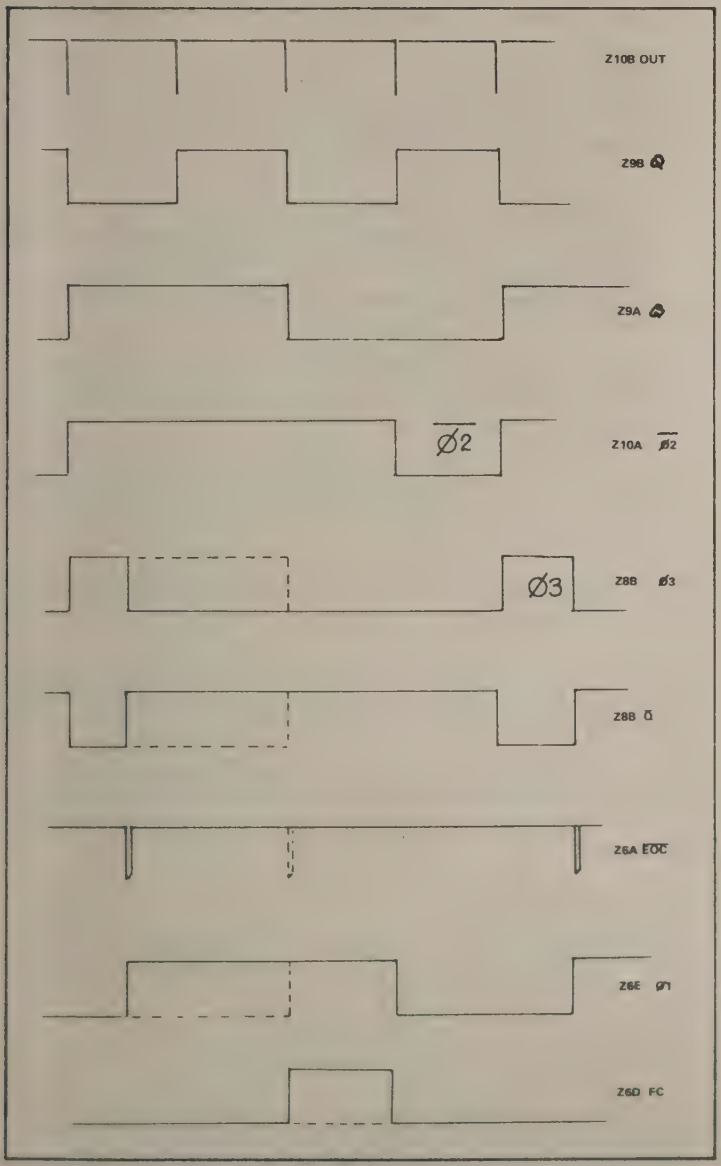


Figure 3-10. Digital Timing Diagrams

3.8 ISO-POLAR REFERENCE GENERATION

The Iso-polar reference generation is accomplished as illustrated in the simplified schematic of Figure 3-11. The generation of correct magnitude of reference voltage for resistance measurements, and the generation of digital control signals $\phi 3(-)$ and $\phi 3(+)$ for negative or positive meter inputs, respectively, have been described previously.

The simplified circuit schematic indicates the operation in two major segments:

1) Generation of a zener-controlled servoed positive reference level, calibrated for full scale by R10.
2) Action by purely passive components to apply either positive or negative levels as required.

Operational amplifier Z3 in the servo loop controlled by Zener CR4, produces a voltage level of 1.0V across the precision resistor network R6 and R7, so that 1.0V or 0.1V is selected for voltage or current measurements, respectively

During Phase 1, while the auto-zeroing action is in process, C18 is charged to the value of selected magnitude (1.0V or 0.1V) by the charging path formed by closed FET switches Q6 and Q4.

During Phase 2, while the unknown meter input is being integrated, the charged capacitor C18 is removed from the circuit.

At the start of Phase 3, if a negative meter input has been sensed, then switch Q7 is closed by $\phi 3(-)$, connecting the positive reference value to the A/D input (in series with the zero correction value stored on C19 during Phase 1.)

If a positive meter input has been sensed, then switch Q5 is closed by 03(+), connecting the high side of C18 to ground reference level. The low side of C18 is then the negative value of reference voltage and is connected to the A/D input as explained above.

3.9 DC/DC CONVERTER*

The battery potential of 7.2 volts is converted by the non-repairable, replaceable DC/DC converter to deliver: +10V and +200V supplies for multimeter operation. A built-in test circuit is provided so that the meter itself may be used to check the battery charged potential.

The battery potential of 7.2 volts is converted by the DC/DC converter to deliver: +10V and +200V supplies for multimeter operation.

The high side of the battery is connected to meter ground, providing the negative 7.2V supply directly from the low side of the battery. The DC input is then converted into an AC signal by the Q14 and Q15 oscillator circuit. One winding output of the oscillator is rectified and filtered to furnish the +10V supply, while another secondary is full wave rectified to furnish the +200V for display supply power

*See Fold-Out Reference Schematic

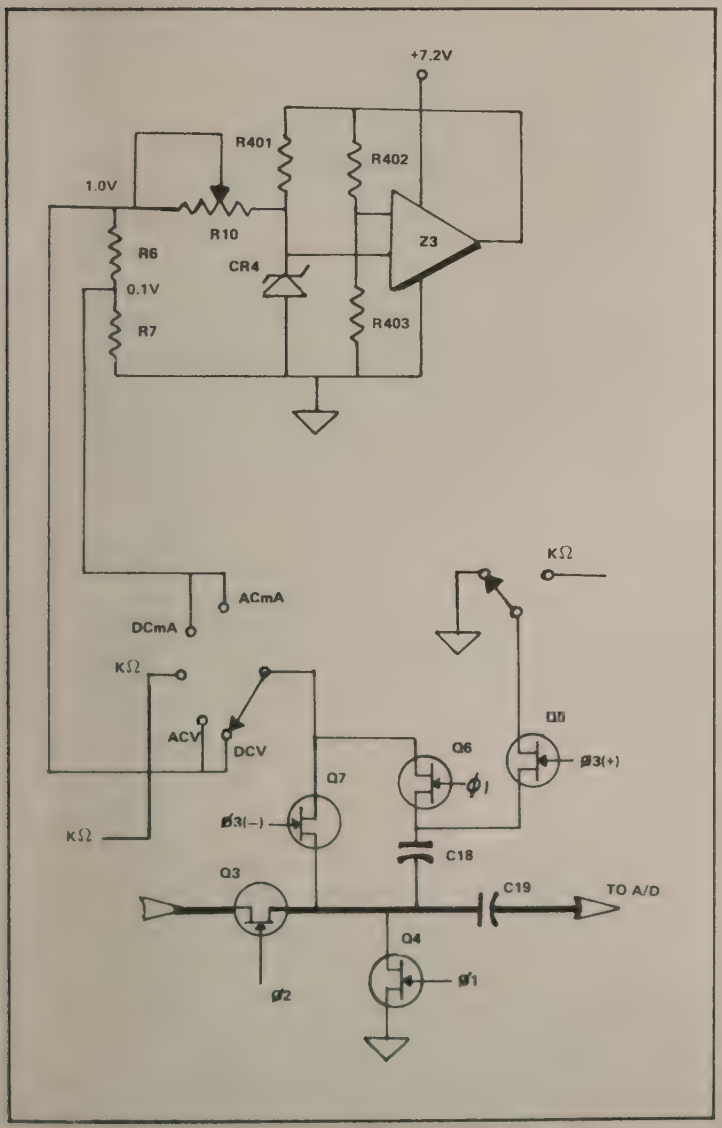


Figure 3-11. Iso-Polar Referencing Voltage Generation Schematic

NOTES

Chapter 4

MAINTENANCE

4.1 GENERAL

CAUTION

The Model 245 Multimeter is covered by a one-year warranty and should be referred to the factory for maintenance within the warranty period. Attempts to make any extensive repairs within the warranty period may invalidate the warranty. If repairs are needed after the warranty period, only qualified technicians should attempt to effect such repairs and should use test instruments and standards calibrated within the accuracy and tolerances of the specifications.

4.2 TROUBLE-SHOOTING FLOW CHART

Should the meter performance indicate a possible need for repair, a well-defined strategy should be used to isolate the cause of trouble. This is illustrated in Figure 4-1. It indicates a sequence of steps and defines a program of actions in terms of standard symbols based on a philosophy of *positive* maintenance. The positive approach isolates to the faulty sections by verifying proper operation of the remaining instrument sections.

4.3 TEST POINTS

The test sequences identified in the chart of figure 4.1 are described in step-by-step detail in the paragraphs that follow. In performing the tests detailed in these paragraphs, the maintenance technician is directed to make measurements at designated test points which have been placed at significant portions in the circuit. The special test points are identified by E-reference numbers, and their locations on the printed circuit board are shown in figure 4.2. Other test points designated in the test procedure paragraphs may be pin terminals of circuit components, and technicians should refer to component data sheets for the pin terminal locations as well as to figure 4.2. Use caution in attaching test leads to avoid accidental shorting of adjacent components. The use of EZ Mini Hook ®, or equivalent is suggested to aid in making good connections.

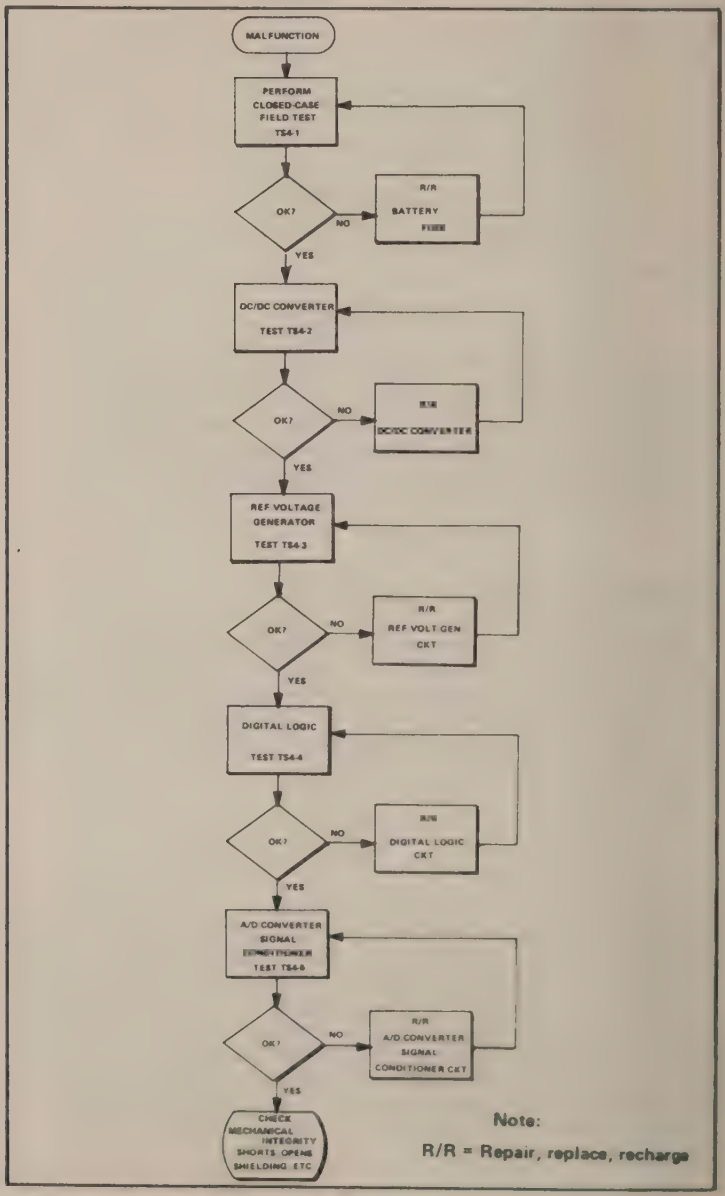


Figure 4-1. Model 245 DMM Trouble Shooting Strategy

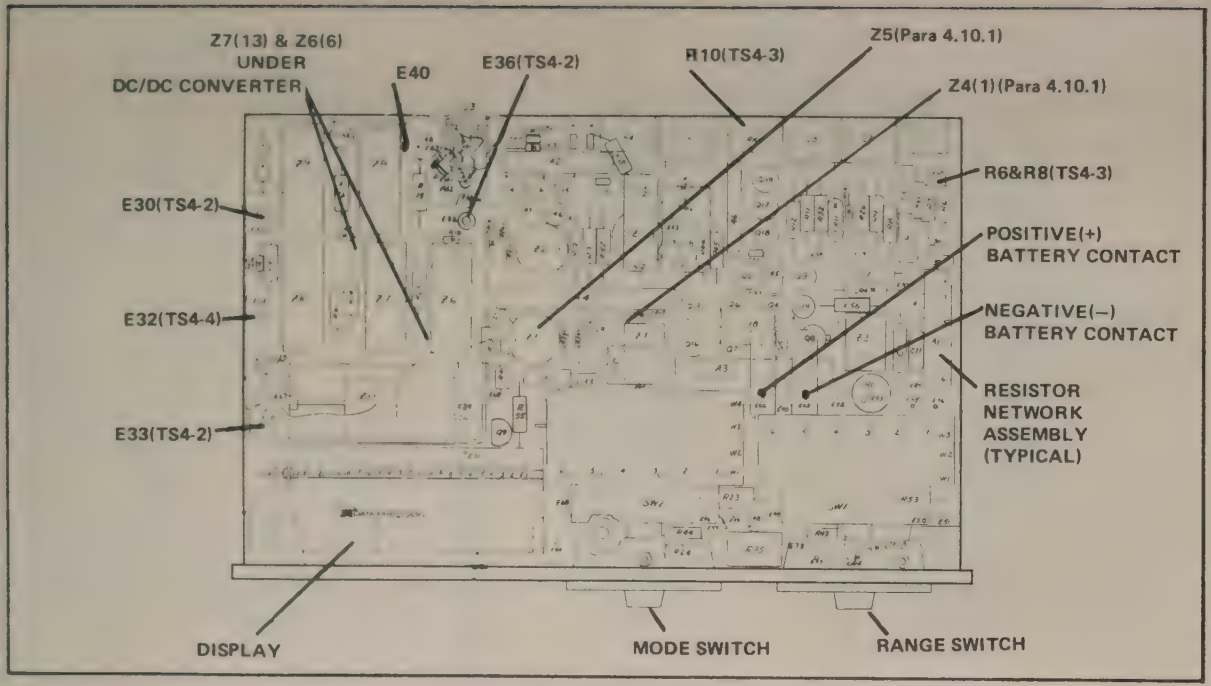
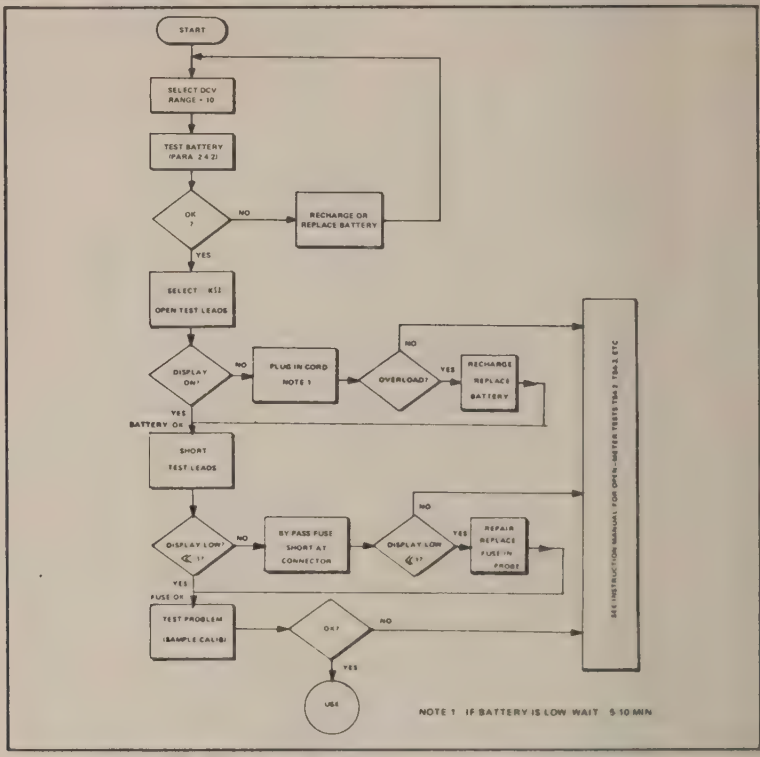


Figure 4-2. Model 245 DMM Main Assembly



Model 245 DMM Field Maintenance Trouble Shooting Strategy

4.4 CLOSED-METER TESTS (FIELD MAINTENANCE) TS4-1

The first test sequence is performed with the "cased" meter. The sequence is fully detailed in the illustration of TS4-1.

4.5 OPEN-METER TEST/MAINTENANCE

4.5.1 General

If the multimeter does not perform correctly after the tests of TS4-1 are satisfactorily completed, then it is likely that repairs to an internal assemply are required. The sequence of such tests is indicated in the overall strategy of figure 4-1, and is identified by a TS number for further reference. Each test sequence paragraph includes the designation of test points, the indications of proper performance, the circuits that are checked when proper performance is observed, and the circuits that should be examined in greater detail when indications of improper performance are recorded. Refer to the fold-out schematic in the back of this manual for complete circuit details, and to Chapter 5 for replacement parts identification.

4.5.2 Removal of Meter Assembly from Case (See Figure 2-1)

The meter assembly is contained on one main PC board. To remove this board from the case:

a) Remove the battery module;
b) Remove the fastening screw from the case underside;
c) Carefully withdraw the meter assembley from the case through the front. Place on insulating surface. Major assemblies are pointed out in figure 4-2.

4.5.3 Applying Power to the Meter Assembly

Power for the multimeter may be obtained by connections to the battery pack with jumpers as shown in figure 4-3. (Be sure that a fully charged battery pack is available for these trouble-shooting test sequences. The battery charger may be connected after the battery has been connected to the circuit.

WARNING

Be sure to maintain the proper polarity relationships as shown in figure 4-3. Improper polarity connection, even if momentary, may result in major component damage. The battery module should be connected before connecting the charger input because the battery acts as a necessary filter for the charger circuit.

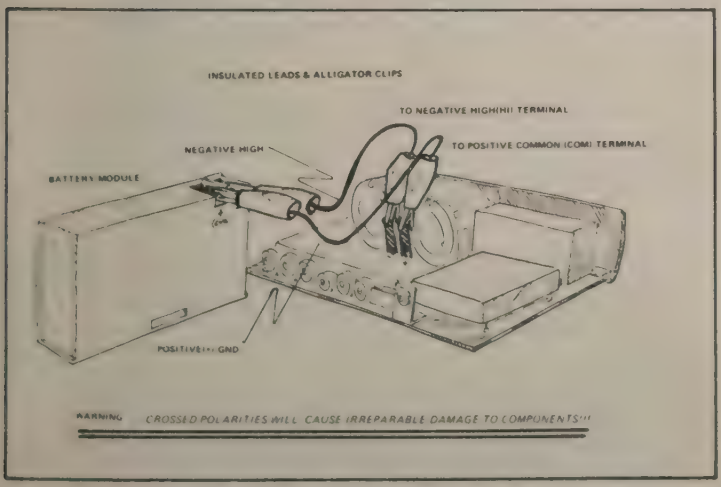

INSULATED LEADS & ALLIGATOR CLIPS
TO NEGATIVE HIGH(HI) TERMINAL
TO POSITIVE COMMON (COM) TERMINAL
NEGATIVE HIGH
BATTERY MODULE
POSITIVE(+) GND
WARNING CROSSED POLARITIES WILL CAUSE IRREPARABLE DAMAGE TO COMPONENTS!!!

Figure 4-3. Connecting Battery Module to Main Assembly Board

4.6 Test Equipment

Test instruments and reference standards needed for the trouble shooting analysis should have the following characteristics:

Parameter	Range	Accuracy	Measure/Generate * M/G
DC Voltage	–10V to +10V	±0.1%	M/G
	+200V	±1 %	M
AC Voltage	100KHz 1 VRMS		
	20KHz 200 VRMS	±0.1%	M/G
	100 VRMS		
	10 VRMS		
	1 VRMS		
Timing Waveforms	Oscilloscope 5 MHz BW	±5%	M
Resistance	0 to 10 MΩ		M/G

*Measure = indicates test instrument. Generate = indicates source instrument

4.7 DC/DC CONVERTER TEST & POWER TS4-2

a) Select KΩ Mode and 10MΩ Range positions
b) Check for the indicated voltages at the test points shown below:

Test Points*	Measure Value
E 36	+10.0V ±1V
E 30	Battery (-7.5V nom)
E 33	+190 to +230V

*Measurements are made with respect to E 40.

c) If all readings are correct the DC/DC converter is operating satisfactorily. An incorrect reading may result from a short circuit in one of the boards driven by the power supply or by a failure within the DC/DC converter.

Unless a battery is shorted or completely discharged, it is unlikely that the -7.2 V supply will be in error, because it is directly connected to the battery. If both the +10V and +200V supplies are out of tolerance, then the fault is probably within the DC/DC Converter module. If only one of the supply levels is in error, then proceed as follows:

d) Turn off power to meter by positioning Mode switch to OFF. Carefully u plug the DC/DC Converter assembly.

WARNING

The +200V supply to terminal E33 from the Converter will remain HOT'. Handle with care. Do not place on conducting surface. Ground the DC/DC converter case to E33.

e) Ground the +200V and the +10V supplies,

f) Measure the resistance to ground at E.33. If zero (essentially a short circuit) then the Display assembly, including flexprint, are suspect.

g) Measure the resistance to ground at E36. If zero (essentially a short circuit) then one of the three analog modules Z3, Z4, or Z5 is suspect.

h) Measure the resistance to ground at E30. If zero, or infinity then one of the digital logic modules is suspect. Furthermore, because they are powered by the battery, it is probable that the faulty logic IC has drawn sufficient current from the battery to cause the etch to be burned through, resulting either in the infinite resistance reading or in the zero reading of a short to ground. Therefore, examine the PC board carefully for evidence of solder burns, and trouble shoot for the faulty logic module.

NOTE

Correct power supply readings do not guarantee correctly driven loads.

i) If the resistance measurement values are satisfactory, then replace the DC/DC Converter with a new one.

4.8 REFERENCE VOLTAGE GENERATOR: TS4-3

a. Select KΩ Mode
b. Measure 1.0000V±0.0001V at R6, R8 junction
c. Attempt to adjust to correct value by R10.

If correct proceed to 4.9. If correct value cannot be obtained by R10 adjustment, then trouble shoot voltage reference generator circuit. See details in fold-out.

4.9 DIGITAL LOGIC: TS4-4

NOTE

In all logic timing waveforms, high levels are at ground potential; low levels are at −7V potential.

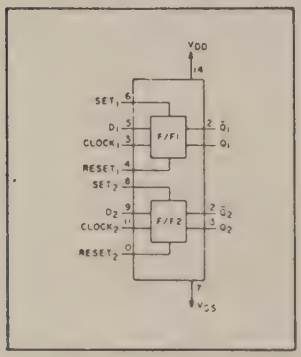
4.9.1 Basic Logic Modules

The Model 245 DMM utilizes three basic logic IC's in its design. Each one is a COS (monolithic silicon) type unit. They are:

a) NAND Gates
b) Exclusive OR Gates
c) D-Type Flip-Flops

Their schematic representations, pin-terminal designations and logic truth tables are defined below for assistance in trouble shooting and fault isolation.

Dual D-Type FLIP–FLOP



TRUTH TABLE

CL*	D	R	S	Q	Q̄
↓	0	0	1	0	1
↑	0	0	1	0	1
↓	1	0	1	1	0
↑	1	0	1	1	0
↓	x	0	0	Q	Q̄
↑	x	0	0	Q	Q̄
x	x	1	0	0	1
x	x	0	1	1	0
x	x	1	1	*	*

NO CHANGE

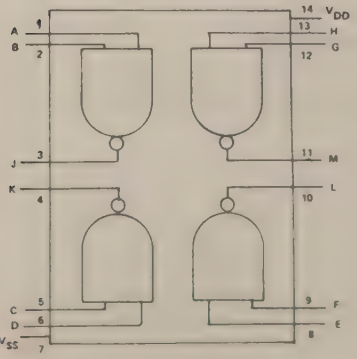
* = INVALID CONDITION

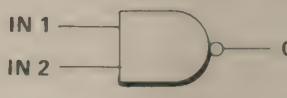
** = FF1/FF2 TERMINAL ASSIGNMENTS

↓ = LEVEL CHANGE

x = DON'T CARE CASE

C /MOS Quad NAND Gate

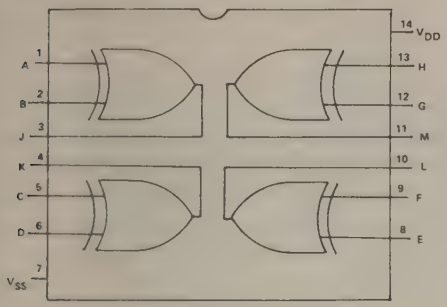




TRUTH TABLE

IN 1	IN 2	OUT
0	0	1
0	1	1
1	0	1
1	1	0

COS/MOS Quad Exclusive OR Gate



TRUTH TABLE

IN 1	IN 2	OUT
0	0	0
0	1	1
1	0	1
1	1	0

4.9.2 Clock

a. Select DCV measuring mode at the Mode Switch.
b. Use an oscilloscope to observe the clock output waveform of approximately 100 KHz at E32. (Note: accurate 100 KHz signal is required for proper multimeter operation, but that adjustment can be made later, using potentiometer R18, accessible through hole in the DC/DC Converter cover).

If frequency is within tolerance (± 1%), the clock circuit is functioning correctly. If not, trouble shoot the clock circuit in the DC/DC converter Module.

4.9.3 Phase Timing Signals

a) Jumper a connection from Z7B pin 13 to the input, pin 6, of Z6B. This will simulate an overload input signal.
b) Use an oscilloscope to trace the waveform generation in the digital logic units and verify the waveforms of figure 3-10. See the detailed schematic at the back of the book for IC pin terminals and for detailed trouble shooting.
c) Observe the overload display on the front panel. If not proper, trace signal trhough chip.

4.9.4 Polarity Logic

a) Ground the input to Z6B. This simulates a negative input signal.
b) Observe the negative polarity sign on the display.
c) Replace jumper connection of a) above with a jumper connecting 7.2V to the input pin 6 of Z6B. This simulates a positive input signal to the meter
d) Observe the change in polarity sign from negative to positive.

If proper performance is not observed, check the polarity flip-flop circuitry and the display circuitry. (See detailed reference schematic).

4.10 A/D CONVERTER & SIGNAL CONDITIONERS: TS4-5

4.10.1 General

The performance of the A/D Converter and the signal conditioners are now checked at the output of buffer amplifier Z4A, pin 1, so that the measuring instrument will not load down the signal. The procedures require the introduction of test signals at the input to the multimeter and checking performance at two places:

a) At the display. Observe readings; check that they are correct.

If satisfactory, then that mode of measurement range scale attenuation, A/D converter, and display segment decoding and indicating are all satisfactory.

b) At the output of Z4A. (If display is not correct).

If satisfactory, then the malfunction may be in the display circuitry, character segment, or in the Z4B and Z5 stages of the A/D Converter.

4.10.2 Fault Analysis Logic

If the output of Z4A is not correct, then judicious cycling of range scales and measurement modes may be able to isolate malfunctioning elements. For example, if a correct value is obtained for only one polarity (and incorrect for the other), then the reference voltage switching circuits should be checked. Malfunctioning character segments may be detected by varying the input over a range, and observing the display. If DC inputs are correct but AC values are not correct, then the malfunction is probably in the AC to DC converter circuitry.

If Both AC and DC voltage measurements are correct on all ranges, but current measurements are incorrect, then the trouble may be isolated to the current shunt. If some DC measurements are correct and some are incorrect, then one may suspect the input attenuator network.

4.11 PROGRAMMED TROUBLE–SHOOTING FLOW DIAGRAMS

Figures 4-4 and 4-5 are step-by-step programs for fault isolation which may be used to supplement the instructions in the previous paragraphs. These trouble-shooting procedures should be performed by qualified technicians because they include the removal and replacement of soldered connections in order to carry out the program to the isolation of faulty components and circuit elements.

CAUTION

If attaching screws are to be replaced, use screws of the same length; longer ones are in danger of contact to high voltage.

Figure 4-4. Trouble-shooting the Digital portion of MODEL 245

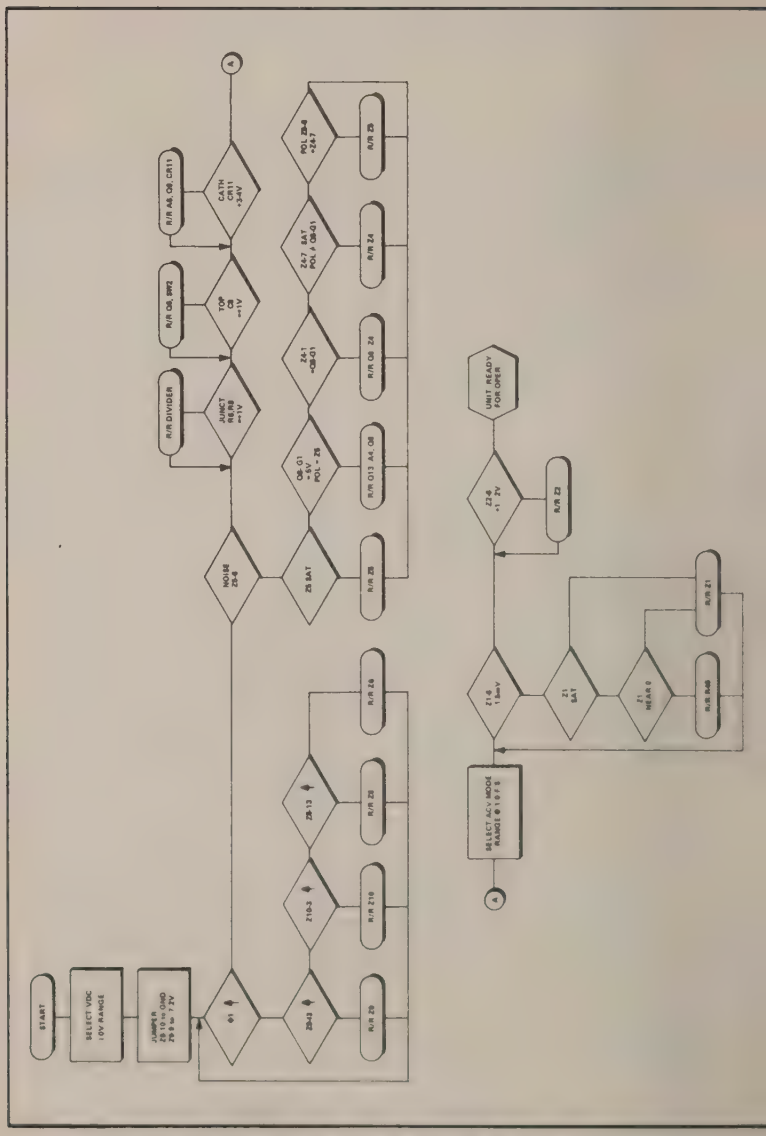


Figure 4-5. Trouble-shooting the Analog portion of MODEL 245

Chapter 5

PARTS LISTS

(Replaceable Parts)

5.1 MAIN PC BOARD ASSEMBLY (See Figure 5-1 for Parts Location.)

REF. DESIG.	DESCRIPTION	PART NUMBER
A1	Network, Input	A48-1009
A2	Network, Resistor	A48-1004
A3	Network, Resistor	A48-1003
A4	Network, Coupling	A48-1008
A6	Network, Resistor	A48-1011
C1	Capacitor, Variable 1.7-6pF	9330
C2, C3	Capacitor, Variable 10-60pF	10S-TRIKO-24-10/60
C4	Capacitor, 0.015uF, 50V, 2%	PD5A153G
C5	Capacitor, 120 pF, 5%	DM10
C6	Capacitor, 1500 pF, 5%	DM7
C7	Capacitor, Variable 2-8 pF	10S-TRIKO-24-2/8
C8	Capacitor, 20 pF, 500V, 5%	
C9	Capacitor, 8 pF, 1000V, 10%	AX75-8pF-1000V
C10	Capacitor, 0.1μF, 400V, 20%	MKT 1813-1/400
C11	Capacitor, .001uF, 1KV	861-Z5U-102M
C13	Capacitor, 220pF, 5%	CN10-221M
C12, C29, C34, C48	Capacitor, 15uF, 10V	ETP2-15/10
C14	Capacitor, 47uF, 3V	ETP2-47/3
C15, C16, C46	Capacitor, 0.47μF, 35V	ETP1-47/35
C17	Capacitor, 0.056uF, 50V, 10%	ACF-50-.056-10
C18	Capacitor, 2uF, 50V, 10%	ACF-50-2.0-10
C19	Capacitor, 100uF, 3V	ETP3/100/3
C20	Capacitor, 1uF, 50V, 10%	ACF-50-1.0-10
C21, C50	Capacitor, 10pF, 50V, 20%	CN10C100M
C23, C33, C47	Capacitor, 0.1uF, 50V	2120GM-050-R104
C30	Capacitor, 0.022uF, 10%	CW20C223K
C32	Capacitor, 2pF, 20% 50V	KDT200
C39	Capacitor, Factory Select	DM10
C40	Capacitor, 68uF, 16V	CY20B103P
C41, C42	Capacitor, 4.7pF	CN10C4R7M
CR1-3, CR5	Diode, 1N4148	
CR12, CR16,18-20,23		
CR4	Diode, Zener reference	A48-1001
CR11, CR15	Diode 1N4004	
CR13, CR14	Diode, low leakage rectifier	A48-1013
	Diode, 1N4001	

5.1 MAIN PC ASS'Y (CONTINUED)

REF. DESIG.	DESCRIPTION	PART NUMBER
Q2	Transistor, 2N3903	
Q3, Q13, Q16	Transistor, FET	A48-1014Y or B
Q17,Q18	Transistor, FET	A48-1014 Y or G
Q8	Transistor, Dual FET	A48-1012
Q9	Transistor, 2N3905	
Q19	Transistor, DTP 203	
Q4	Transistor, U233	
Q5, 6	Transistor, FET	A48-1014G
Q7	Transistor, FET	A48-1014B
R1	Resistor, 910K, 2W, 5%, C.C.	
R2	Resistor, 1M, 1%	RN70C
R3	Resistor, 1M, 1/4W, 5%, C.C.	
R4	Resistor, Variable, 1K, 20%	3359W-1-1002
R6	Resistor, Precision 9K (Note 3)	A48-1005-1
R7	Resistor, Precision 1K (Note 3)	A48-1005-2
R8	Resistor, Precision, 52K (Note 3)	A48-1005-3
R9	Resistor, Factory Select	RN55C
R10, R35	Resistor, Variable, 200Ω, 10%	3359W1-201
R11,R12,19,55	Resistor, 27K, 1/4W, 20%, C.C.	
R13	Resistor, 47Ω, 1/4W, 20%, C.C.	
R15, R16	Resistor, 2.7M, 1/4W, 20%, C.C.	
R23	Resistor, 30Ω, 1/2W, 5%, C.C.	
R24, R53	Resistor, 100K, 1/4, 20%, C.C.	
R25	Resistor, 18K, 1/4W, 20%, C.C.	
R26	Resistor, 39K, 1/4W, 20%, C.C.	
R27, 40, 41, 47	Resistor, 15K 1/4, 10%	
R28	Resistor, Precision 90.00Ω (Note 4)	A48-1007-1
R29	Resistor, Precision 9.000Ω (Note 4)	A48-1007-2
R30	Resistor, Precision 0.9000Ω (Note 4)	A48-1007-3
R31	Resistor, Precision 0.1000Ω (Note 4)	A48-1007-4
R32	Resistor, 180Ω, 1/4W, 10% CC	
R33	Resistor, 620Ω, 1/8W 5% CC	
R34, R5	Resistor, 1M, 1/8W, 5%, CC	
R42	Resistor, Factory Adjust	
R59	Resistor, 15K, 1/4W, C.C.	
R43, 44	Resistor, 10K, 1%	RN55C
R45	Resistor, 47M, 1/4W, C.C.	
R46, R14	Resistor, 470K, 1/4W, C.C.	
R52	Resistor, 3.9K, 1/4W, C.C.	
R54	Resistor, 6.2M, 1/8W, C.C.	
R57	120K, 1/8W, 5% C.C.	
R58	2000M, 1/2W, 20%, C.C.	
Z1	Amplifier, Operational	N5556T
Z2	Amplifier, Operational	LM301AH
Z3	Amplifier, Operational	LM741CN
Z4	Amplifier, Operational	N5558V
Z5	Amplifier, Operational	LM709C
Z6	Integrated Circuit	MC-14507
Z7-9	Integrated Circuit	MC-14013
Z10	Integrated Circuit	MC-14011
Z13	MOS 4 DIG DISP CTR/DECODER	A48-1010

Note 3: Must be replaced as a matched set A48-1005
4: Must be replaced as a matched set A48-1007

LIST OF MANUFACTURERS FOR MANUFACTURER – SOURCE COMPONENTS

PART NO.	MFG. NAME
A48-1009, A48-1004, A48-1003, A48-1008, A48-1011	Data Precision
9330	Johanson
10S-TRIKO-24-10/60	TRIKO
PD5A153G	ELPAC
10S-TRIKO-24-2/8	TRIKO
AX75-8pF-1000V	Radio Material Corp. Type C
MKT 1813-1/400	ERO
861-Z5U-102M	Radio Material Corp. Type B
CW10-221M	US Capacitor/Centralab
ETP2-15/10	ERO
ETP2-15/10	ERO
ETP1-47/35	ERO
ACF-50-056-10, ACF-50-2.0-10	Active & Passive Components, Inc.
ETP3/100/3	ERO
ACF-50-1.0-10	Active & Passive Components, Inc.
CW10C100M	US Capacitor/Centralab
2120GM-050-R104	Varidyne
CW20C223K	US Capacitor/Centralab
KDT200	Kahgan Components
ETP4-68/16	ERO
CW10C4R7M	US Capacitor/Centralab
A48-1001	Data Precision
A48-1013	Data Precision

PART NO.	MFG. NAME
A48-1014Y or B	Data Precision
A48-1014Y or G, A48-1012	Data Precision
DTP 203	Dionics
U233	Teledyne
A48-1014G	Data Precision
A48-1014B	Data Precision
HB9145	Allen Bradley
3359W-1-1002	Bourns
A48-1005-1, A48-1005-2	Data Precision
A48-1005-3	Data Precision
3359W1-201	Bourns
A48-1007-1	Data Precision
A48-1007-2	Data Precision
A48-1007-3	Data Precision
A48-1007-4	Data Precision
BB1055	Allen Bradley
N5556T	Signetics
LM301AH	National Semiconductor
LM741CN	National Semiconductor
N5558V	Signetics
LM709CH	National Semiconductor
MC-14507	Motorola
MC-14013, MC-14011	Motorola
A48-1010	Data Precision

DISPLAY & PROBE

Display Assembly	4½ Digit Display	D47-1000	Data Precision
Probe Fuse	3AG-2A	AGW-2	Buss

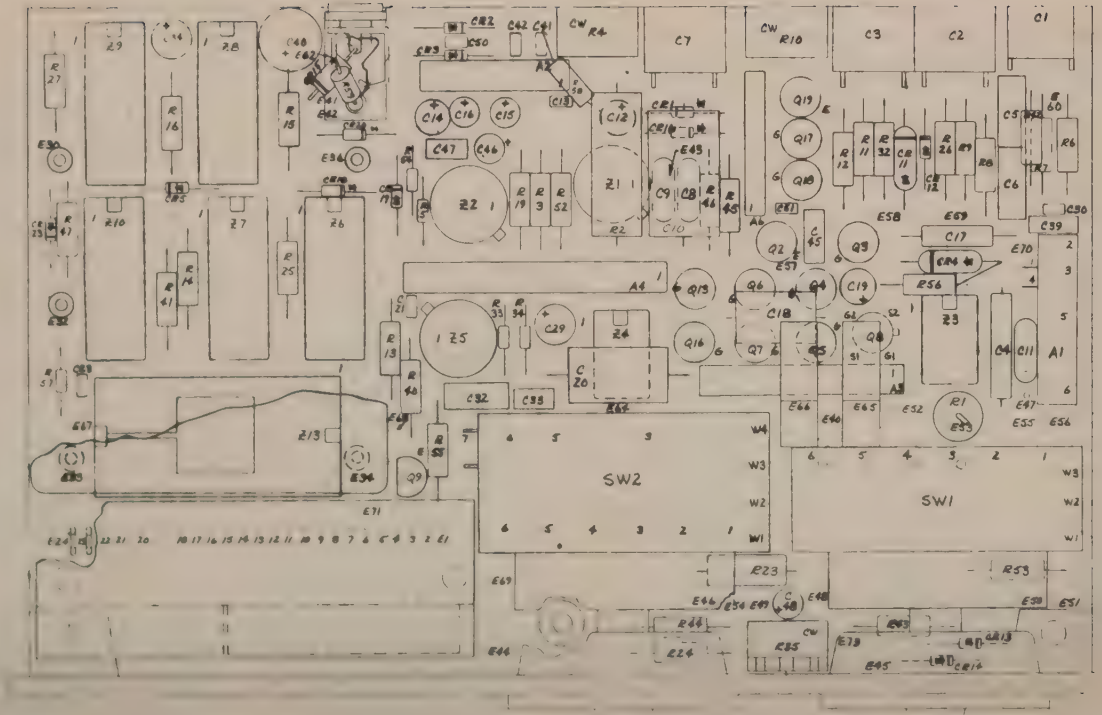


Figure 5-1. Main PC-Board Assembly , identifying replaceable components. (DC/DC Converter removed)

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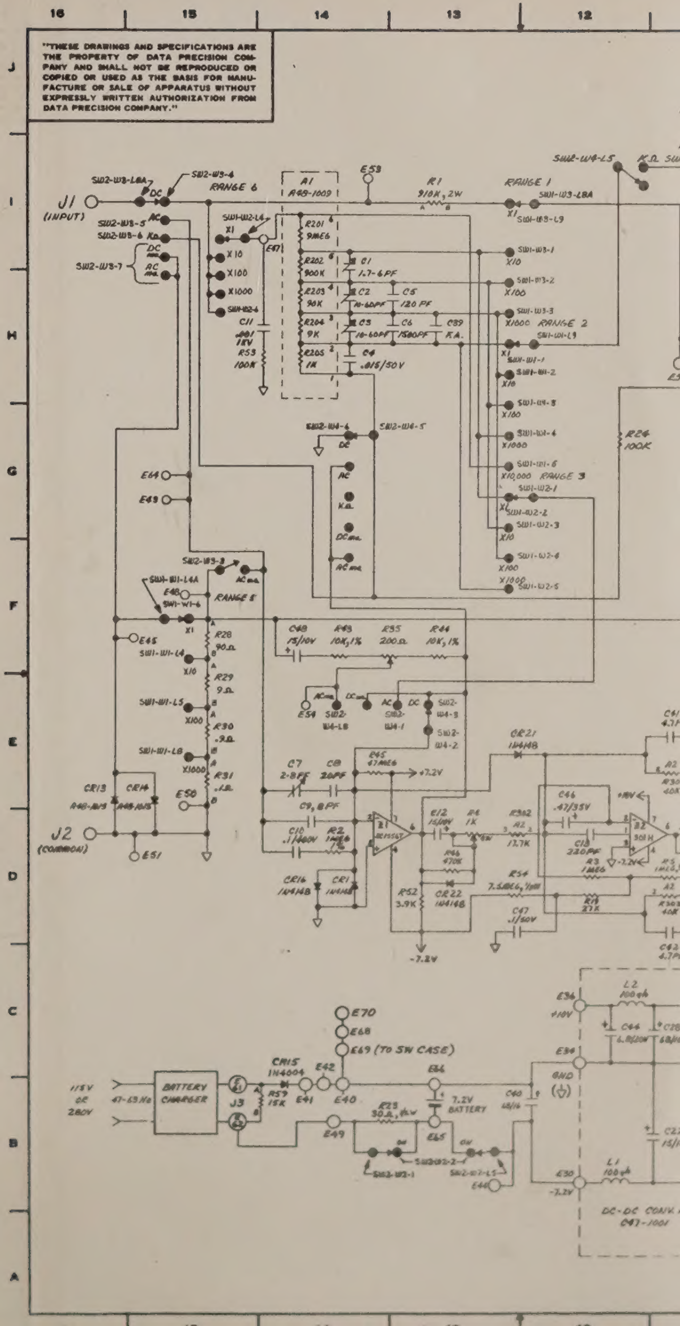
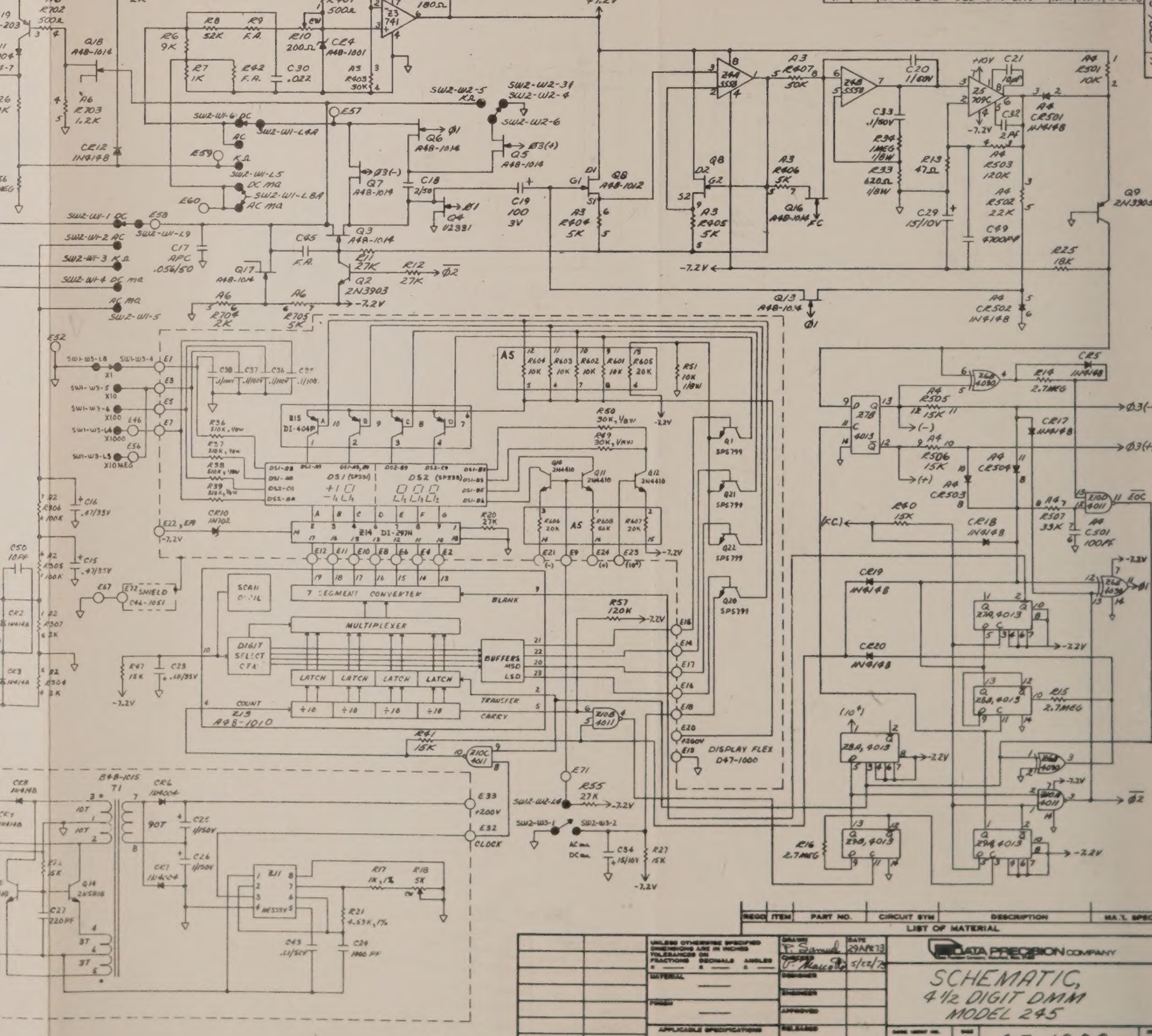

J1 (INPUT)
J2 (COMMON)
RANGE 6
RANGE 1
RANGE 2
RANGE 3
RANGE 5
A1 A48-1009
R1 910K, 2W
R201 9ME6
R202 900K
R203 90K
R204 9K
R205 1K
C1 1.7-6PF
C2 10-60PF
C5 120 PF
C3 10-60PF
C6 1500PF
C39 F.A.
C4 .015/50V
C11 .001 1KV
R53 100K
R24 100K
C48 15/10V
R43 10K, 1%
R35 200Ω
R44 10K, 1%
R28 90Ω
R29 9Ω
R30 .9Ω
R31 .1Ω
CR13
CR14
CR21 1N4148
R45 47ME6
+7.2V
C7 2-8PF
C8 20PF
C9, 8PF
C10 .1/400V
R2 1ME6 1%
CR16 1N4148
CR1 1N4148
R52 3.9K
CR22 1N4148
R46 470K
R54 7.5ME6, 1/2W
C46 .47/35V
C18 220PF
R3 1ME6
C47 .1/50V
-7.2V
E70
E68
E69 (TO SW CASE)
CR15 1N4004
R59 15K
J3
BATTERY CHARGER
115V OR 230V
47-63 Hz
R23 30Ω, 1/2W
7.2V BATTERY
C40 68/16
L2 100μh
L1 100μh
C44 6.8/20V
+10V
GND
DC-DC CONV. A
C47-1001

REVISIONS					
REV	ECO	DESCRIPTION	DWN	APPL'S	DATE
6		REVISED PER ECO 036-2114			
H		REVISED PER ECO 035-2114			6-26-73



+7.2V
+10V
-7.2V
A6 R701 2K
A6 R702 500Ω
A6 R703 1.2K
A6 R704 2K
A6 R705 5K
Q18 A48-1014
CR12 1N4148
R6 9K
R7 1K
R8 52K
R9 F.A.
R42 F.A.
C30 .022
R10 200Ω
CR4 A48-1001
A3 R401 500Ω
A3 R402 5K
A3 R403 30K
Z3 741
R32 180Ω
SW2-W1-6 DC
SW2-W1-L4A
SW2-W1-L5
SW2-W1-L8A
SW2-W1-L9
SW2-W1-1 DC
SW2-W1-2 AC
SW2-W1-3 KΩ
SW2-W1-4 DC ma
SW2-W1-5
SW2-W2-5 KΩ
SW2-W2-3
SW2-W2-4
SW2-W2-6
E57
E58
E59
E60
Q6 A48-1014
Q5 A48-1014
Q7 A48-1014
Q4 U2331
Q3 A48-1014
Q17 A48-1014
Q2 2N3903
C17 APC .056/50
C45 F.A.
R11 27K
R12 27K
C18 2/50
C19 100 3V
Q8 A48-1012
A3 R404 5K
A3 R405 5K
A3 R406 5K
A3 R407 50K
Q16 A48-1014
Z4A 5558
Z4B 5558
C20 1/60V
C33 .1/80V
R34 1MEG 1/8W
R33 620Ω 1/8W
R13 47Ω
Z5 709C
C21 10pF
C32 2pF
A4 R501 10K
A4 CR501 1N4148
A4 R503 120K
A4 R502 22K
C29 15/10V
C49 4700PF
R25 18K
Q9 2N3905
Q13 A48-10.4
A4 CR502 1N4148
E52
SW1-W3-L8
SW1-W3-4
X1
SW1-W3-5 X10
SW1-W3-6 X100
SW1-W3-L4 X1000
SW1-W3-L3 X10MEG
E1 E3 E5 E7 E46 E56
C38 C37 C36 C35 .1/100V
R36 R37 R38 R39 510K, 1/8W
Z15 DI-404P
DS1 (SP331)
DS2 (SP338)
A5 R604 10K R603 10K R602 10K R601 10K R605 20K
R51 10K 1/8W
R50 30K, 1/8W
R49 30K, 1/8W
Q10 2N4410
Q11 2N4410
Q12 2N4410
Q1 SPS799
Q21 SPS799
Q22 SPS799
Q20 SPS799
Z14 DI-297N
R20 27K
A5 R606 20K R608 56K R607 20K
E22, E19
CR10 1N702
E12 E11 E10 E8 E6 E4 E2
E21 (-) E9 E24 (+) E25 (10⁴)
A2 R306 100K
C16 .47/35V
A2 R305 100K
C15 .47/35V
C50 10PF
CR2 1N4148
A2 R307 2K
CR3 1N4148
A2 R304 2K
E67
E72 SHIELD C46-1051
SCAN OSC'L
7 SEGMENT CONVERTER
MULTIPLEXER
DIGIT SELECT CTR
BUFFERS MSD LSD
LATCH
÷10
COUNT
TRANSFER
CARRY
BLANK
Z13 A48-1010
R47 15K
C23 .68/35V
R57 120K
E15 E14 E17 E16 E18 E20 +200V E13
DISPLAY FLEX D47-1000
Z10B 4011
Z10C 4011
R41 15K
E71
R55 27K
SW2-W2-L4
SW2-W3-1
SW2-W3-2
AC ma DC ma
C34 15/10V
R27 15K
B48-1015 T1
10T 10T 90T 3T 3T
CR8 1N4148
CR7 1N4148
CR6 1N4004
CR7 1N4004
C25 1/150V
C26 1/150V
R22 15K
Q14 2N5818
C27 220PF
E33 +200V
E32 CLOCK
Z11 NE555V
R17 1K, 1%
R18 5K
R21 4.53K, 1%
C43 .01/50V
C24 1000 PF
Z6B 4030
CR5 1N4148
R14 2.7MEG
Z7B 4013
A4 R505 15K
A4 R506 15K
CR17 1N4148
A4 CR504
A4 CR503
Ø3(-)
Ø3(+)
(-)
(+)
R40 15K
(FC)
CR18 1N4148
A4 R507 33K
A4 C501 100PF
Z10D 4011
EOC
Z6C 4030
Ø1
CR19 1N4148
CR20 1N4148
Z7A 4013
Z8B 4013
R15 2.7MEG
(10⁴)
Z8A 4013
Z6A 4030
Z10A 4011
Ø2
R16 2.7MEG
Z9B 4013
Z9A 4013

REQD	ITEM	PART NO.	CIRCUIT SYM	DESCRIPTION	MAT'L SPEC

LIST OF MATERIAL

NEXT ASSY	USED ON	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TOLERANCES ON FRACTIONS DECIMALS ANGLES	DRAWN P. Samuel DATE 29APR73
APPLICATION		MATERIAL	CHECKED P. Marcotte 5/22/73
		FINISH	DESIGNER / ENGINEER / APPROVED / RELEASED
		APPLICABLE SPECIFICATIONS	WEIGHT

DATA PRECISION COMPANY

SCHEMATIC,
4 1/2 DIGIT DMM
MODEL 245

SIZE D — 45-1000 — REV H

SCALE — ACCOUNT NO. — SHEET 1 OF 1

DATA PRECISION

Data Precision Corporation, Audubon Road, Wakefield, Ma. 01880

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